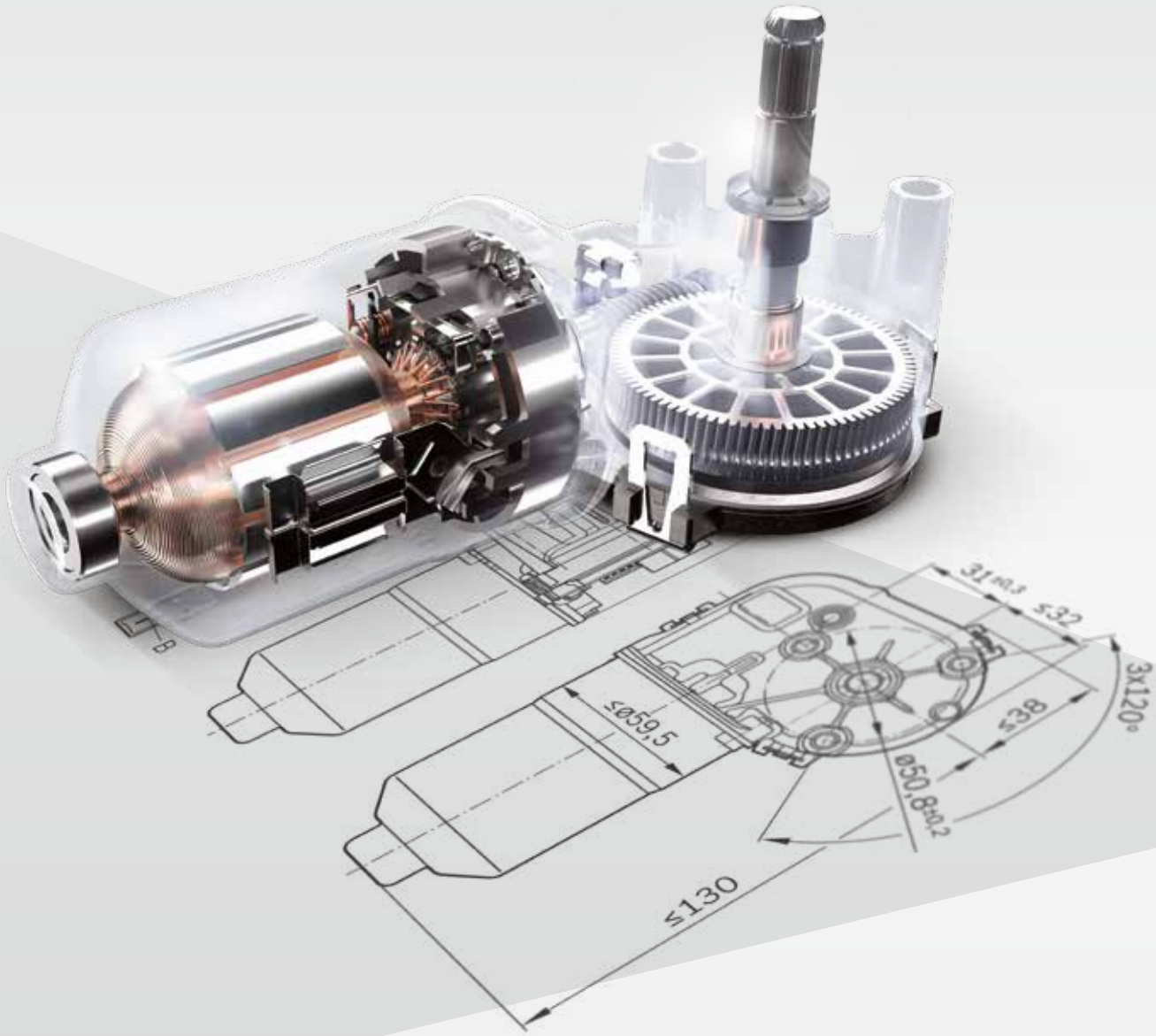
2019 | 2020

BOSCH
Invented for life

Electric motors



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The right drive for your projects
– Bosch electric motors

Electric motors from Bosch encourage movement in product development

With its competence, Bosch, as one of the leading global developer and manufacturer of automotive technology, has proved itself millions of times over in mobile applications. As a development partner to various industrial branches, Bosch is aligned to the requirements of its customers. Thus, Bosch electric motors are also the ideal solution for many applications outside of the automobile. The total of its advantages are immediately obvious, where quality, reliability and competitive prices (through high volume production) are called for.

Industrial customers in particular, expect to have competent contact partners at their suppliers. To this end, an independent engineering team has been set up. Bosch engineers will advise and support you in the application engineering for D.C. motors, blowers and pumps.

Your personal contact for consulting you can find on our website.

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Notes

This catalogue lists the standard parts supplied with all the technical information usually required by design engineers to select the most suitable motor for their particular requirements. These motors were originally designed for use in motor vehicles.

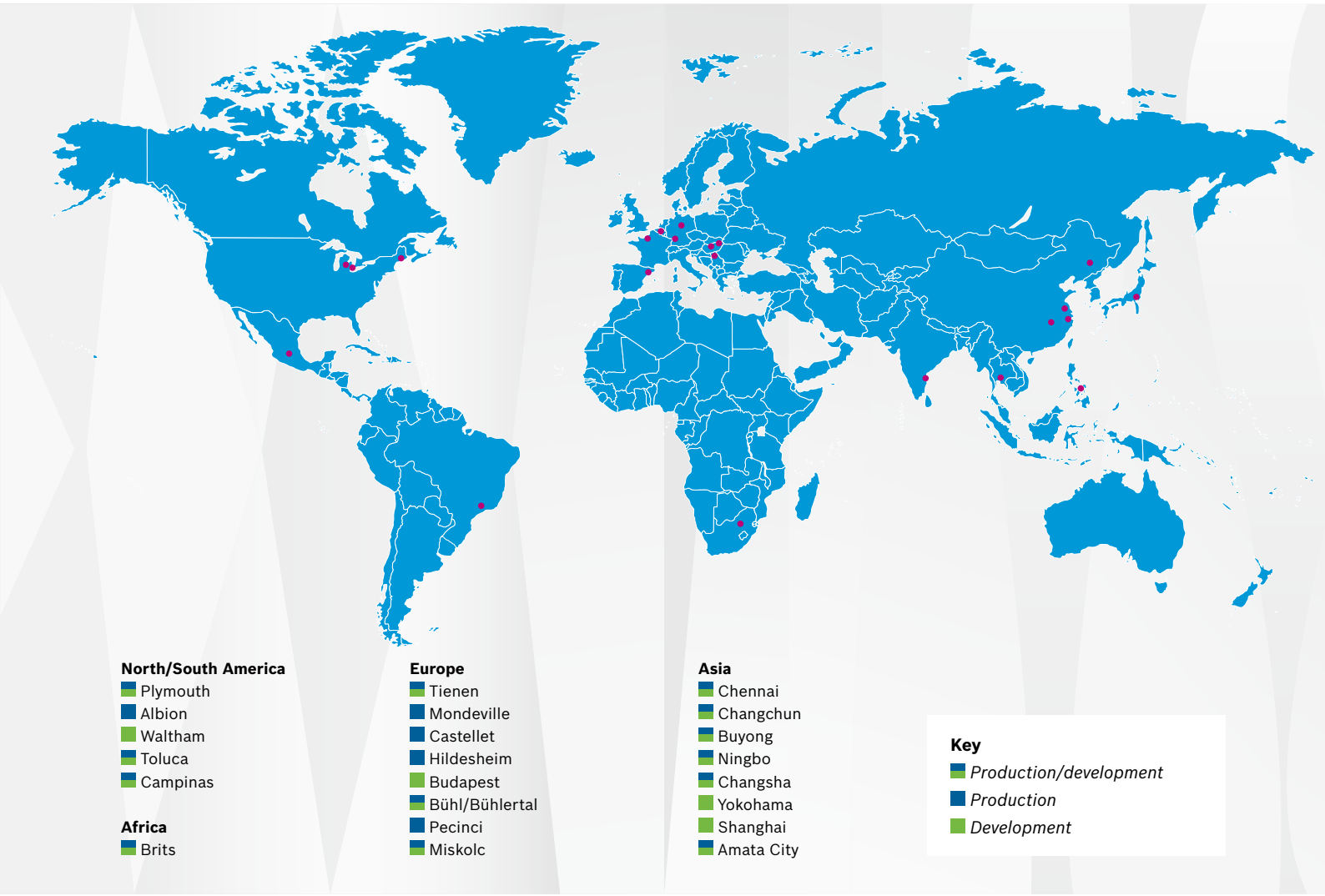
We highly recommend that Bosch be consulted first before you use motors for any applications other than those specified, particularly in the case of other requirements, loads, or environmental conditions.

Subject to change.
Product pictures shown in this catalogue are generic and examples for specific product families. The offer drawings for quoted products shall prevail.

Unlimited service – Bosch electric motors

The worldwide competent partner for industrial applications

As one of the largest manufacturer of electric motors in Europe, Bosch provides its customers with a comprehensive range of products including brushless D.C. motors and brush-type D.C. motors.
Bosch electric motors are developed for the automotive industry and installed into automobiles and commercial vehicles as drives for wiping systems, engine cooling and passenger compartment air-conditioning as well as for the adjustment of windows, sliding roofs and seats.
The Bosch electric motors referred to here are permanent-magnet-excited D.C. motors. They excel on account of an excellent power/weight ratio, a broad working range and through outstanding flexibility for adaptation to different requirements and installation situations. In addition to this they are characterized by features such as low noise volume and robustness (see D.C. motors without transmission).
Bosch plants around the globe operate according to the stringent, internationally-binding Bosch quality guidelines, which only permit products for series production that have been well-proven in tough endurance tests. Profit from the strongly competitive products of mass production.



Customer orientation in development, production and sales

Innovative technology from the automotive industry

- **Many million times well proven and reliable Bosch quality –** As a leading developer and manufacturer of automotive technology Bosch is also experienced in various applications beside the automotive industry.
- **Bosch electric motors are well known for reliability –** They are available in a light and compact design, and provide a high power density and long service life.
- **Price and performance, that match up –** Bosch offers competitive prices due to high volume production and continuous technical improvements.

Individual solutions for your application

- **The right solution for every requirement –** Due to a variety of different designs and sizes, the Bosch range of electric motors provides a great deal of flexibility for installation and use. Bosch electric motors operate in a D.C. voltage range of 12 to 24 Volt. They are also optionally available with and without Hall elements.
- **Successful application examples –** Power-operated hospital beds, wheel chairs, garage-door drives, lawnmowers, locking systems and output systems, electric mopeds and lots more.

Professional customer service

- **All-encompassing customer orientation –** Right from the very start, Bosch engineers provide their support and advice in the application engineering for D.C. motors, blowers or pumps.
- **Global Bosch Standards –** Bosch guarantees worldwide uniform production and quality standards.
- **Technical information –** Comprehensive information on Bosch electric motors is available in our catalogue. Apart from this, you can find more technical details online at www.bosch-ibusiness.com.

Parameter explanation

Nominal values

Nominal value
Value of a variable (e.g. voltage, current, resistance ...) according to which a motor, blower, or pump, or its characteristics and parts are specified or according to which they are designated.

Power consumption P_1

$$P_1 = U \cdot I$$

P_1 Power consumption in W
U Voltage in V
I Current in A

Output power P_2
For motors the output power P_2 is always given.

$$P_2 = 2\,\frac{\pi}{60} \cdot M \cdot n$$

P_2 Output power in W
M Torque in Nm
n Rotational speed in min^{-1}

Efficiency η
Efficiency refers to the relationship between mechanical output P_2 and electrical power input P_1.

$$\eta_2 = \frac{P_2}{P_1}$$

Example
Theoretically, a nominal voltage of 24 V and a rated current of 35 A result in a power input of P_1:
$P_1 = U_N \cdot I_N$; P_1 = 24 V · 35 A; P_1 = 840 W.
This power consumption P_1 and the output P_{2N} (see Fig. page 7) determined from the characteristic-curves chart are used to calculate the efficiency η:

$$\eta = \frac{P_{2N}}{P_1} = \frac{600\ W}{840\ W} = 0{,}71 = 71\%$$

Rated torque M_N
The motor's rated torque is calculated from:

$$M_N = \frac{60}{2\pi} \cdot \frac{P_{2N}}{n_N}$$

M_N Rated torque in Nm
P_{2N} Rated power output in W
n_N Rated speed in min^{-1}

Rated speed n_N
Rated speed refers to the speed of a motor supplied with rated voltage and driven at a rated output.

Direction of rotation
When looking at the motor's shaft end, clockwise operation is deemed to be right-handed rotation.
For motors with two shaft ends, the shaft end opposite the commutator determines the direction of rotation.

Short-circuit values
The current consumed by the motor in case of short-circuit (when armature is braked to standstill), is the maximum current I_{max}.
When a short circuit occurs, the maximum torque M_A (breakaway torque) is effective.

IP degrees of protection

Valid for electrical equipment of road vehicles as under IEC 60529 and DIN 40050, Part 9.

- Protection of electrical equipment within housing against influence of solid foreign bodies including dust.
- Protection of electrical equipment within housing against ingress of water.
- Protection of people against touching of moving mechanical parts within housing.

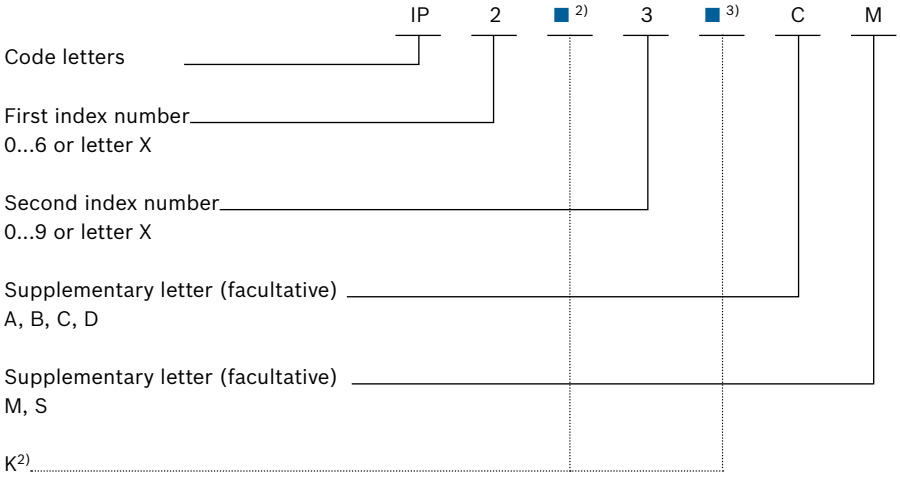
Fastening

- Housing fastening: By means of screws on the motor or transmission housing. Blowers are fastened in a similar manner, either to the drive motor or the air shroud.
- Flange mounting: The motor's drive-end support has a two or three-hole flange, or the front side contains three or four threaded holes for fastening.

Cooling

- Internal natural cooling: open-type design, without fan.
- Internal natural cooling: open-type design, with separate fan.
- Internal forced-air cooling: open-type design, with externally-driven fan.
- Surface natural cooling: closed design, without fan.
- Surface natural cooling: closed design, with separate fan.

IP-code structure



If an index number is not given, then the letter "X" must be substituted (i.e. "XX", if both index numbers are missing).
Additional and/or supplementary letters can be omitted without any substitution:

[2] The supplementary letter "K" is placed either immediately after the first index numbers 5 and 6 or immediately after the second index numbers 4, 6 and 9.

[3] During the water test for example: IP16KB protection against ingress of solid foreign bodies with a diameter ≥ 50 mm, protection against powerful spray water at high pressure, protection against being touched by fingers.

Explanations of IP code

1. Index number and supplementary letter K	Protection of electrical equipment against ingress of foreign bodies	People	2. Index number and supplementary letter K	Protection of electrical equipment against ingress of water	Letter (facultative)	Protection of people in event of contact with hazardous parts	Letter (facultative)	
0	Not protected	Not protected	0	Not protected	A	Protection against contact with back of hand	M	Motion of moving parts Teile [3]
1	Protection against foreign bodies Ø ≥ 50 mm	Protection against contact with back of hand	1	Protection against vertical droplets	B	Protection against contact with fingers	S	Standstill of moving parts Teile [3]
2	Protection against foreign bodies Ø ≥ 12.5 mm	Protection against contact with fingers	2	Protection against droplets, 15° Inclination	C	Protection against contact with tools		
3	Protection against foreign bodies Ø ≥ 2.5 mm	Protection against contact with tools	3	Protection against spray water	D	Protection against contact with wire		
4	Protection against foreign bodies Ø ≥ 1.0 mm	Protection against contact with wire	4	Protection against spray water				
5K	Dust-protected	Protection against contact with wire	4K	Protection against spray water with increased pressure				
6K	Dust-proof	Protection against contact with wire	5	Protection against spray water				
			6	Protection against powerful spray water				
			6K	Protection against powerful spray water with increased pressure				
			7	Protection against temporary immersion				
			8	Protection against permanent immersion				
			9K	Protection against high pressure/vapor pressure cleaning				

Operating modes (VDE 0530)

Continuous operation S 1
Operation with constant load condition, the duration of which is sufficient to reach the thermal steady-state condition.

Parameters for curve inspection

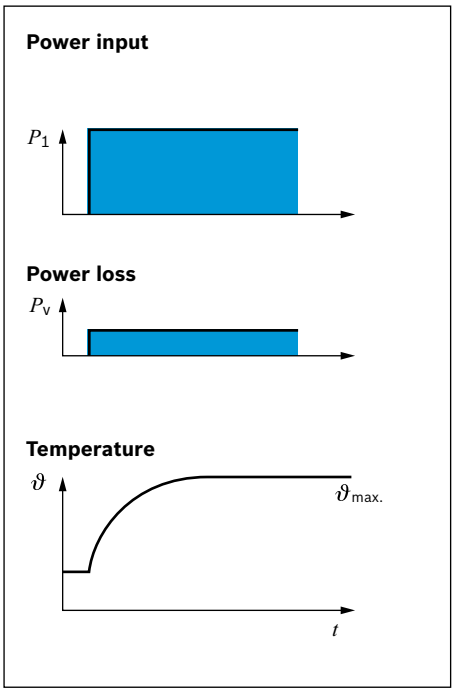
P_1	Power input
P_V	Power loss
ϑ	Temperature
ϑ_{max}	Highest temperature
t_B	Load period
t_r	Relative on period (as percentage)
t_S	Duration
t_{St}	Standstill period

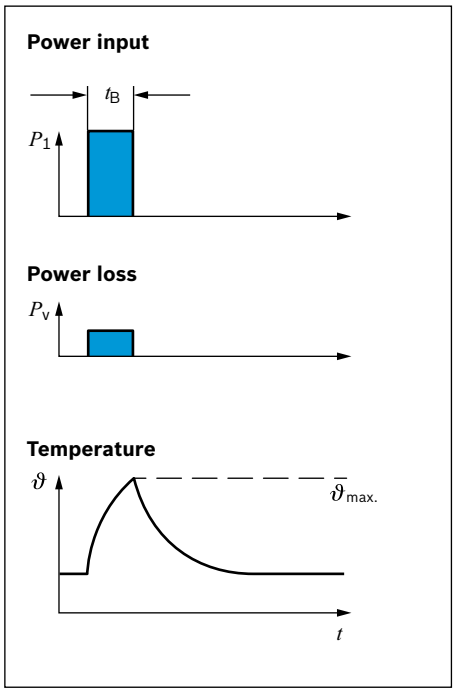
Short-term operation S 2
Operation with constant load condition, which does not last long enough however to enable the thermal steady-state condition to be reached, and a subsequent pause, which lasts long enough for the motor temperature not to deviate more than 2 K from the coolant temperature.

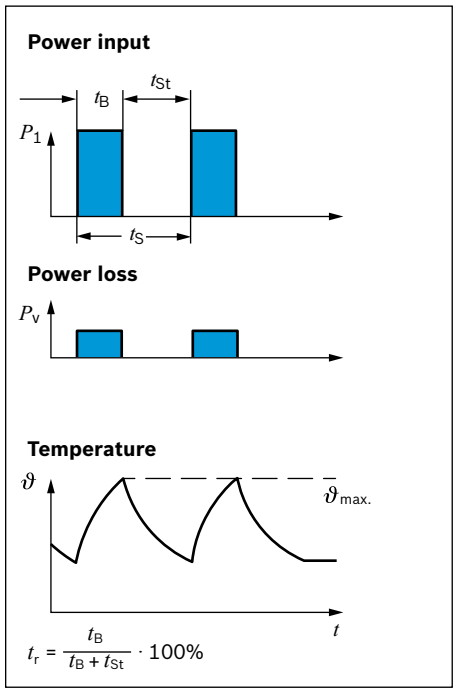
Example: S 2 – 60 min
(The stated time refers to 60 minutes of operation at normal rating)

Intermittent operation S 3
Operation, comprised of a sequence of similar cycles, each of which encompasses a time with constant load and a pause, whereby the startup current does not exert any perceptible influence on heating.

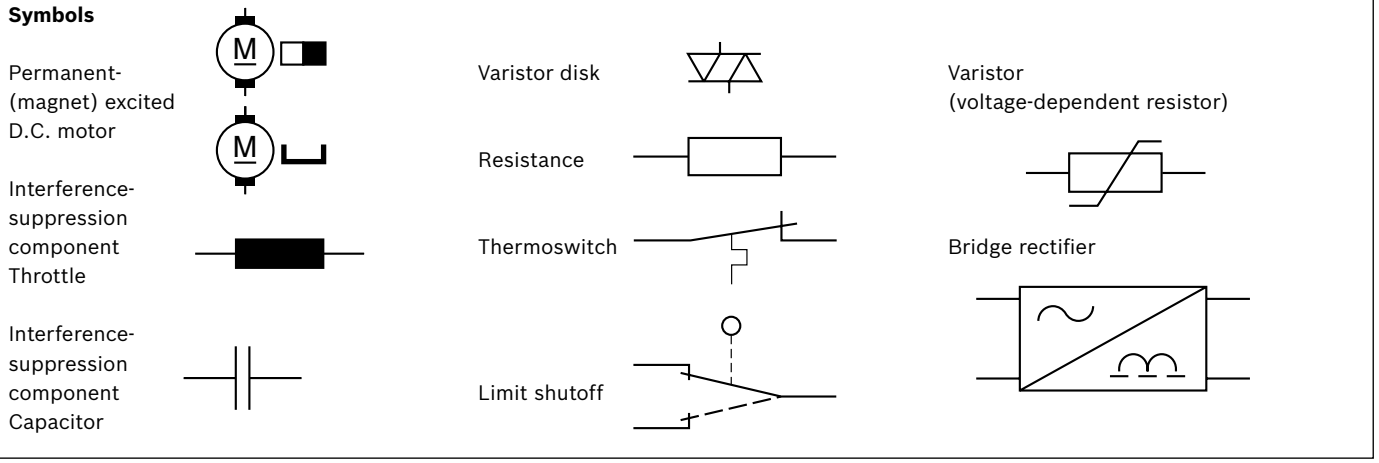
Example: S 3 – 10%
(Stated percentage refers to on period)







Symbols

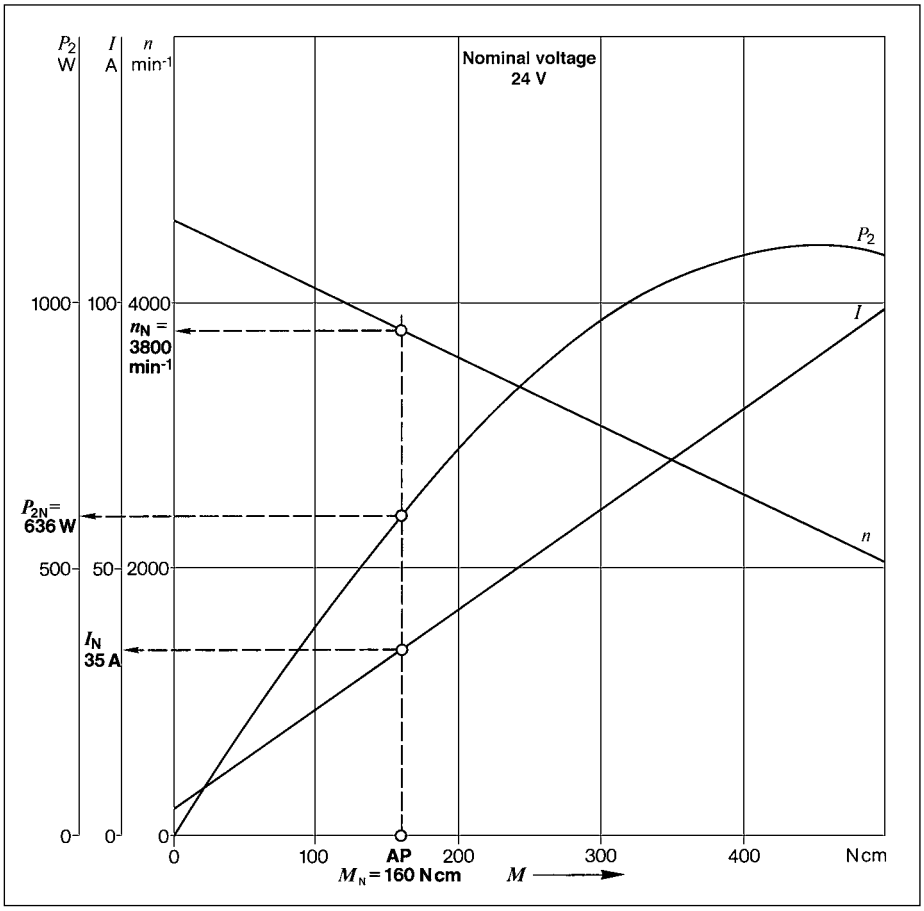


Characteristic curves

With a specified working point of 160 Ncm one plots a vertical line to the torque axis. The intersecting points of these vertical lines with the various characteristic curves result in the operating data for the rated speed n_N, rated current I_N and mechanical output P_{2N}.

Explanation of characteristic curve evaluation
AP Working point
M Torque
P_2 Power output
I Current
n Rotational speed

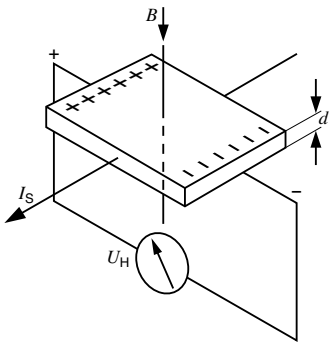
Example:
Given: M_N = 160 Ncm.
Found: n_N = 3.800 rpn (min^{-1}).
P_{2N} = 636 W and I_N = 35 A.



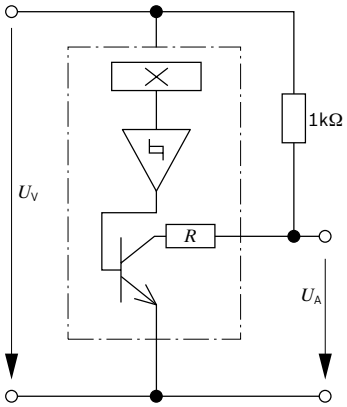
Motors with Hall sensor

Hall effect

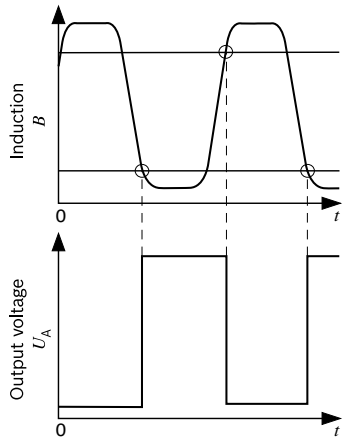
Hall effect
d Thickness of chip



Circuit



Characteristic curves



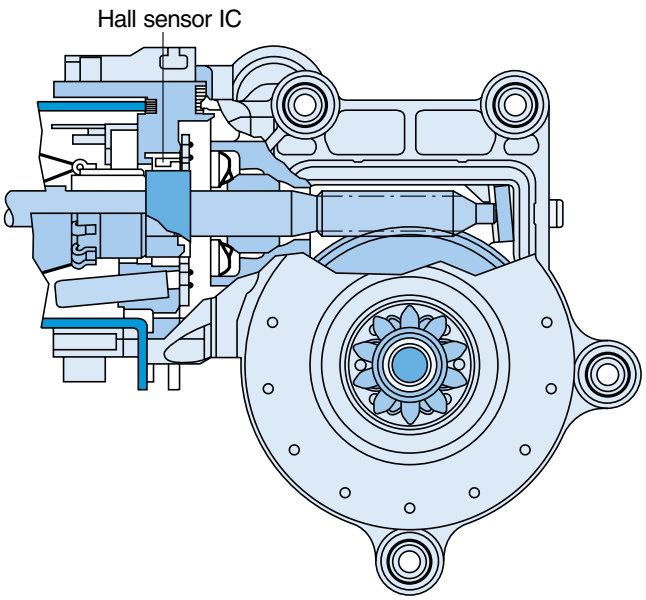
If a current I_S flows through a chip, a Hall voltage U_H is generated transverse to the direction of the current, the size of which is proportional to the magnetic induction B (vertical to I_S) and the current I_S.
The Hall voltage U_H is made up of:

$$U_H = R_H \cdot \frac{I_S \cdot B}{d}$$

R_H Hall-constant factor

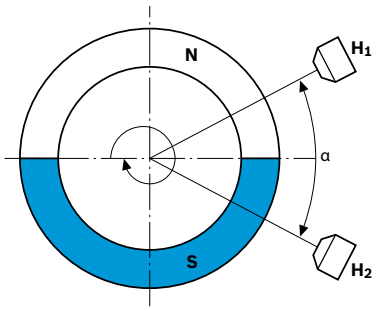
Since the resulting Hall voltages are extremely small, they are amplified.
When using silicon Hall elements, the circuit for signal processing (e.g. a Schmitt trigger with subsequent driver) are integrated directly onto the same chip. This component is then designated a Hall-IC. The output is a transistor with open collector, with which a switching function is realized.

Permanently connected to the armature shaft is a magnetic ring, the magnetic field of which permeates the Hall element. When the armature shaft rotates, the magneto-motive-force direction in the Hall element changes. The output transistor is then either switched through or open.

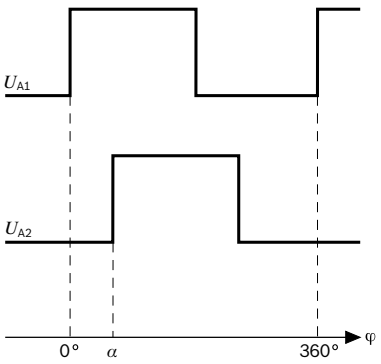


Hall-effect applications in D.C. motors
By counting the generated output-voltage pulses, one can determine the number of rotations and thus the speed. If the rotational motion is converted into a linear motion, it then becomes possible to monitor the adjustment travel exactly. If there are two Hall generators installed offset to each other at a specific angle α in a motor, then the direction of rotation can also be determined.

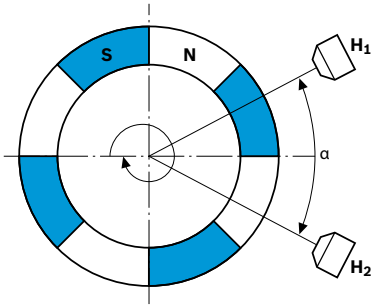
Basic arrangement in motor with 2-pole ring magnet



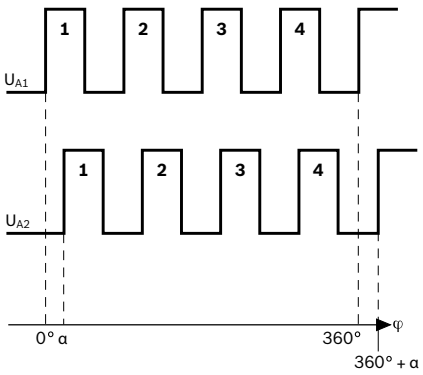
Output signals, 1 armature rotation



Basic arrangement in motor with 8-pole ring magnet



Output signals, 1 armature rotation



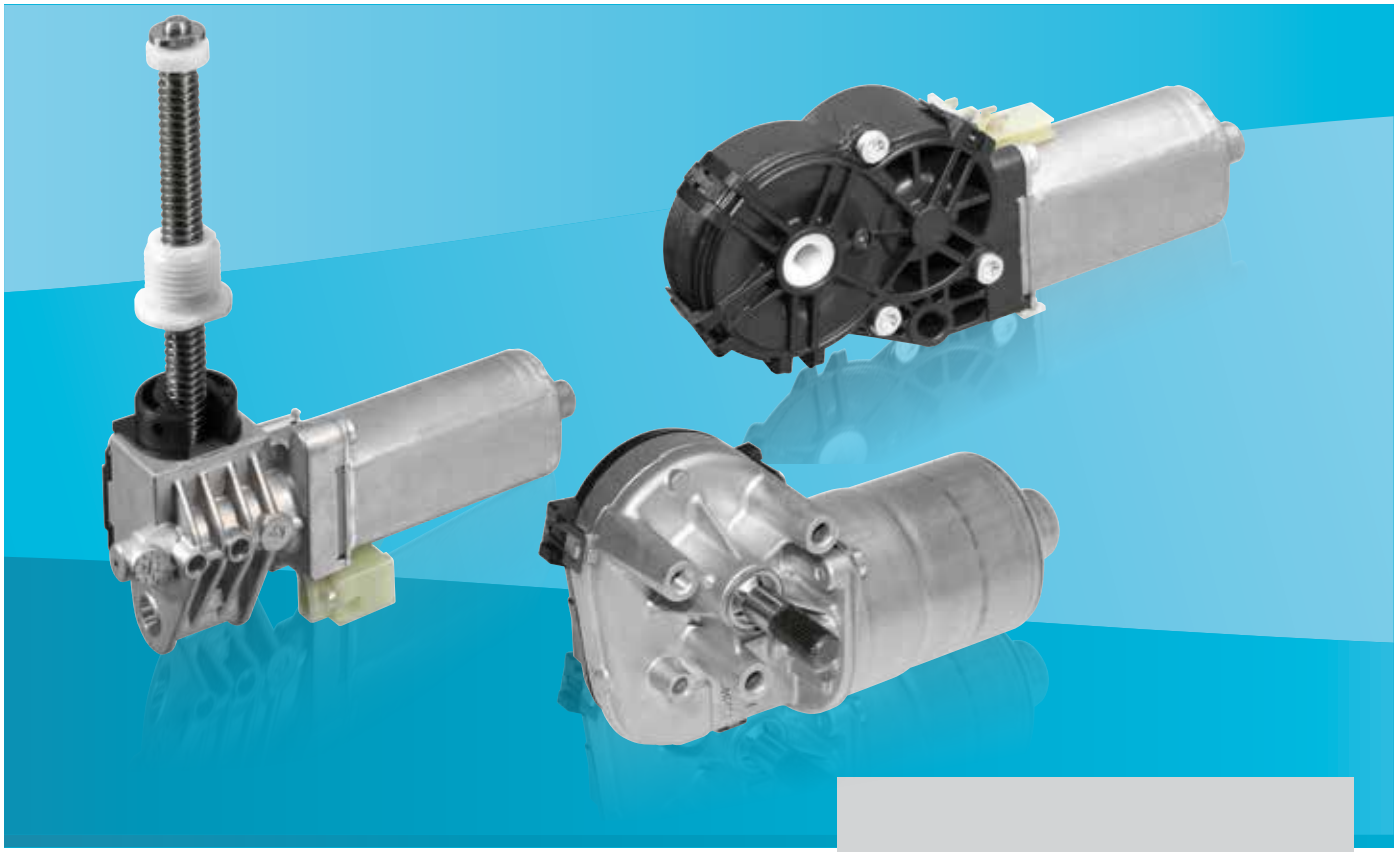
Basic arrangement in motor

H_1, H_2	Hall generator
N	North pole
S	South pole
α	Angle between the two Hall generators

Output signals

U_{A1}	Output voltage of first Hall generator
U_{A2}	Output voltage of second Hall generator
α	Angle between the two Hall generators
φ	Rotational angle

D.C. motors with transmission



Bosch electric motors with transmission provide suitable solutions for almost every application. They provide a wide range of performance and are highly versatile in their application. The new generation of Bosch adjustment motors have a compact design in terms of installation space and weight. In addition to this, they are characterized by features such as low noise volume and robustness.
The desired speed can easily be regulated by changing the voltage. The direction of rotation can be inverted by changing over +/–.
Maximum torque is available during the startup phase.

Application examples

Automotive technology:
Flap positioning for climate control, air proportioning and distribution, wiper motors, power-window motors, seat-adjustment motors, adjustment motors

Industrial applications:
Control motors, garage-door drives, locking systems, furniture, medical technology etc.

Product features

- Wide range of permanently-excited motor-and-gear assemblies
- D.C. voltage range from 12 to 24 Volt
- Available with and without self-locking feature

Advantages for your application

- A multitude of different sizes and designs for greater flexibility
- Robust and reliable quality
- High reliability
- Favorable price/performance ratio

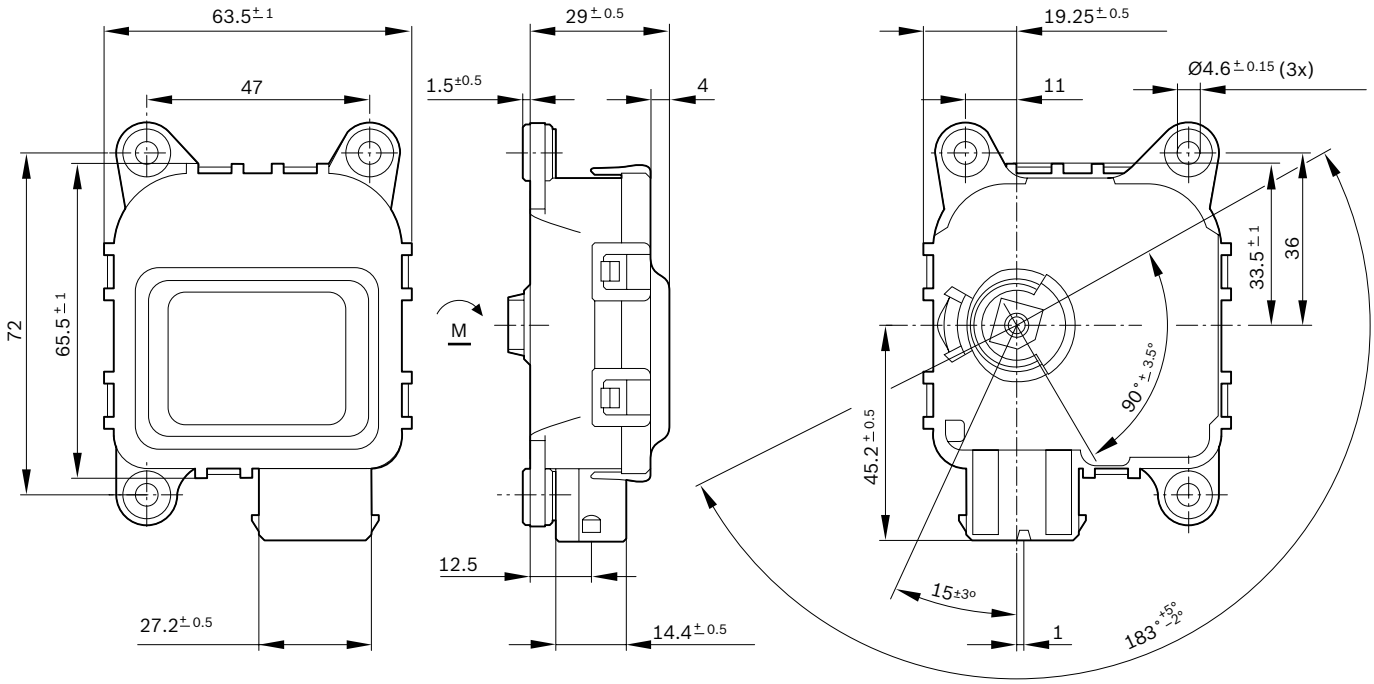
VMC

Family features:

- With and without potentiometer
- Operation mode: S2
- Direction of rotation: CCW/CW
- Compact and robust design

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Direction of rotation	Degree of protection	Signal	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm				Poti				
12 V	0 132 801 142	0.3	0.18	7	0.4	0.9	310:1	CCW/CW	IP 40	No	W2	S1	C1	P2
	0 132 801 169	0.2	0.15	4.5	0.4	0.9	405:1	CW/CCW	IP 40	Yes	W1	S3	C1	P5
	0 132 801 156	0.2	0.13	6.5	0.3	0.9	310:1	CW/CCW	IP 40	No	W2	S4	C1	P4
24 V	0 132 801 143	0.3	0.10	6	0.4	0.9	405:1	CCW/CW	IP 40	No	W3	S1	C1	P3
	0 132 801 141	0.3	0.10	6	0.4	0.9	405:1	CCW/CW	IP 54	Yes	W1	S2	C1	P1

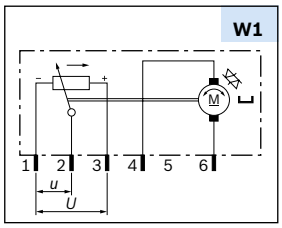
D1



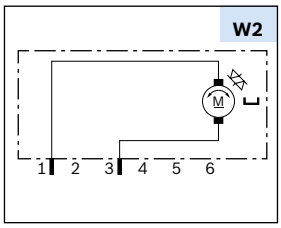
VMC

Wiring diagram (W)

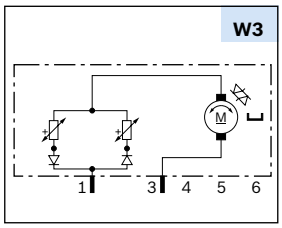
W1



W2

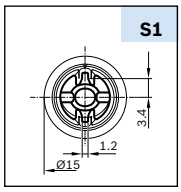


W3

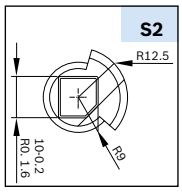


Drive end (S)

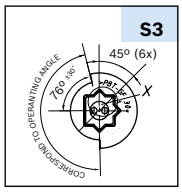
S1



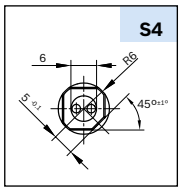
S2



S3

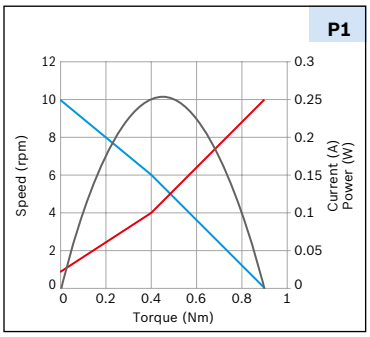


S4

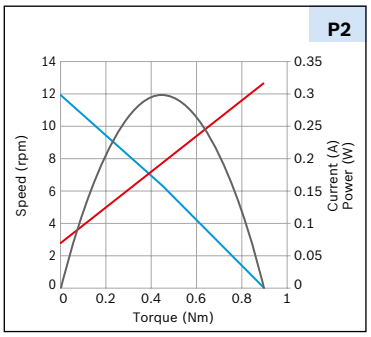


Performance curve (P)

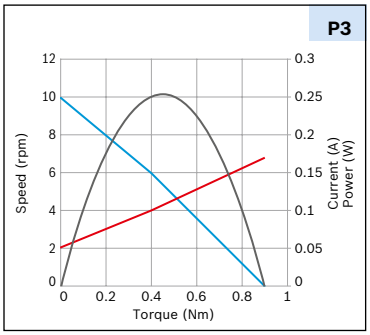
P1



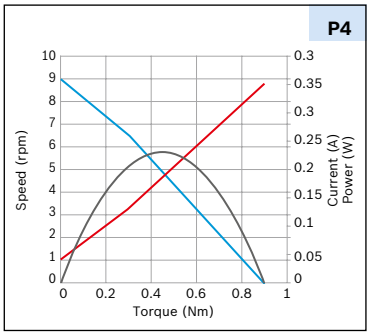
P2



P3



P4



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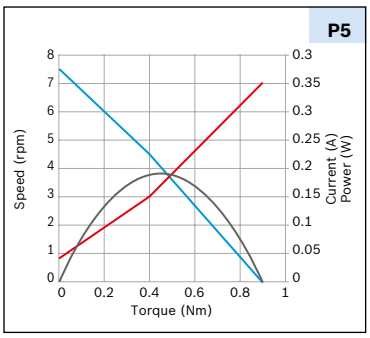
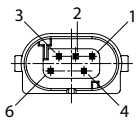


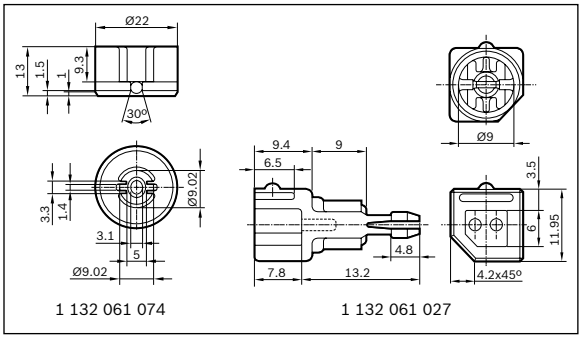
Mating connector (C)

C1



Housing: RB-1 928 403 095
Locker: –
Terminal: 928999-1

Accessories



1 132 061 074

1 132 061 027

AHC1

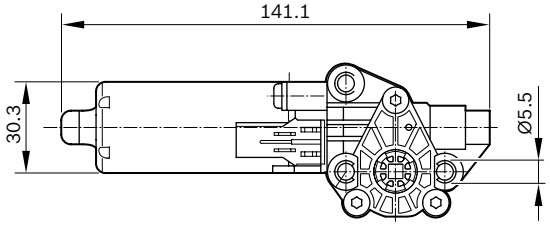
Family features:

- With and without hall sensor
- Degree of protection: IP 50
- Operation mode: S2
- Hollow shaft
- Direction of rotation: CCW/CW

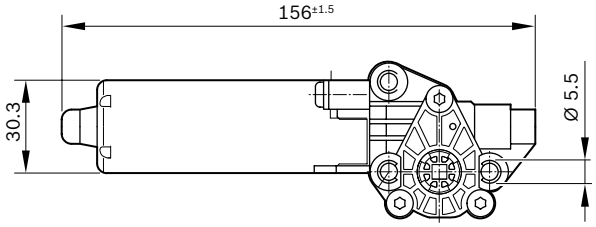
Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Signal	Side**	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm		Hall						
12 V	0 390 201 900	8.8	5	845	0.1	1.05	27:4	No	R	D1	W1	S1	C1	P1
	0 390 201 912	8.8	5	845	0.1	1.05	27:4	No	L	D1	W1	S1	C1	P1
	0 390 201 902	8.8	5	845	0.1	1.05	27:4	Yes	R	D1	W2	S1	C2	P1
	0 390 201 914	8.8	5	845	0.1	1.05	27:4	Yes	L	D1	W2	S1	C2	P1
	0 390 203 371	12.9	4	411	0.3	1.5	27:4	Yes	L	D2	W2	S2	C2	P6
	0 390 201 901	8.6	5	820	0.1	1.5	27:4	No	R	D2	W1	S1	C1	P2
	0 390 201 903	8.6	5	820	0.1	1.5	27:4	Yes	R	D2	W2	S1	C2	P2
	0 390 201 915	8.6	5	820	0.1	1.5	27:4	Yes	L	D2	W2	S1	C2	P2
	0 390 203 370	6.6	3.8	210	0.3	2.8	28:2	Yes	L	D2	W5	S2	C2	P7
	0 390 203 431	13.2	7	63	2	5.8	50:1	Yes	L	D3	W3	S3	C2	P3
	0 390 203 389	2.4	2	75	0.3	1.8	29:1	Yes	L	D1	W7	S2	C2	P8
24 V	0 390 203 314	8.8	3.2	841	0.1	1.85	27:4	No	R	D2	W4	S2	C1	P4
	0 390 203 315	8.8	3.2	841	0.1	1.85	27:4	No	L	D2	W4	S2	C1	P4
	0 390 203 316	8.8	3.2	841	0.1	1.85	27:4	Yes	R	D2	W3	S2	C2	P4
	0 390 203 317	8.8	3.2	841	0.1	1.85	27:4	Yes	L	D2	W3	S2	C2	P4
	0 390 203 386	15.6	4.8	99.5	1.5	11	50:1	2x Hall*	L	D4	W6	S3	C1	P5

* Optional (0 986 196 002) / **gear housing left: L, gear housing right: R

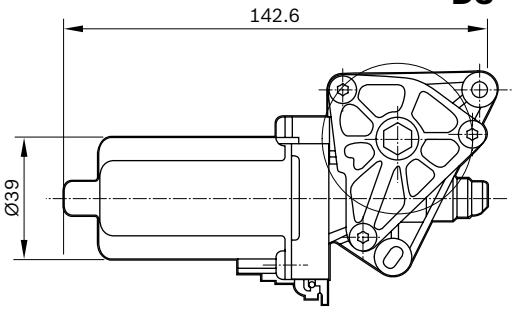
D1



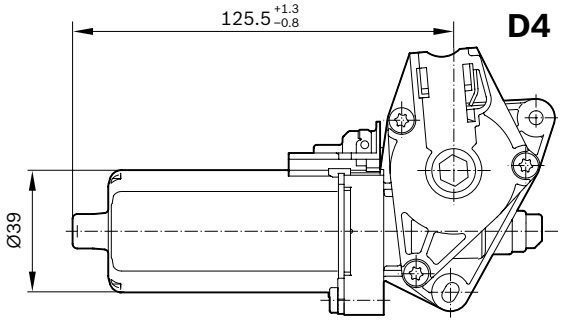
D2



D3



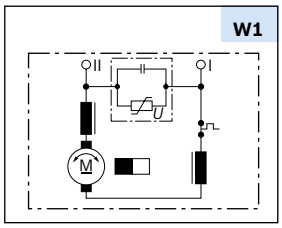
D4



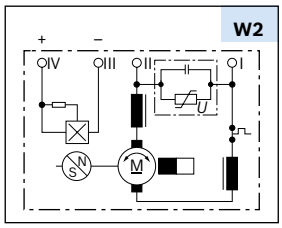
AHC1

Wiring diagram (W)

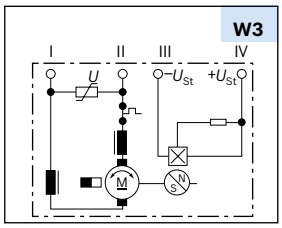
W1



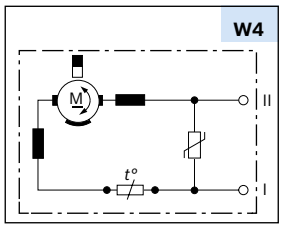
W2



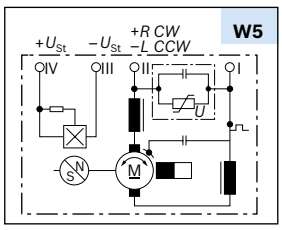
W3



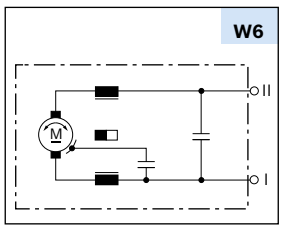
W4



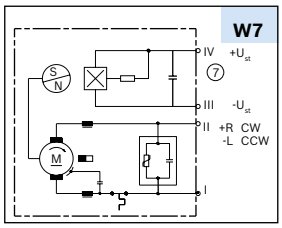
W5



W6

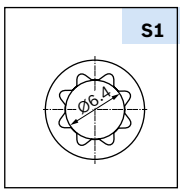


W7

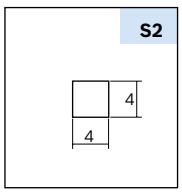


Drive end (S)

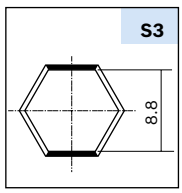
S1



S2

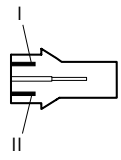


S3



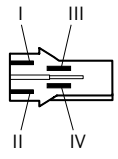
Mating connector (C)

C1



Housing: TE 968182-1
Locker: TE 0-9868183-1
Terminal: TE JPT 0-9827768-1 (x2) / Micro-Timer III

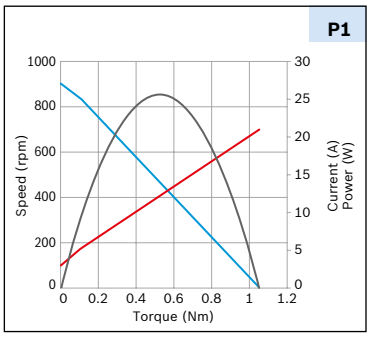
C2



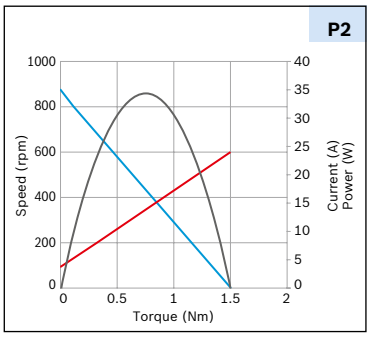
Housing: FCI 3 023 59 01
Locker: TE-0968183-1
Terminal: TE JPT 0-9827768-1 (x2) / Micro-Timer III

Performance curve (P)

P1



P2



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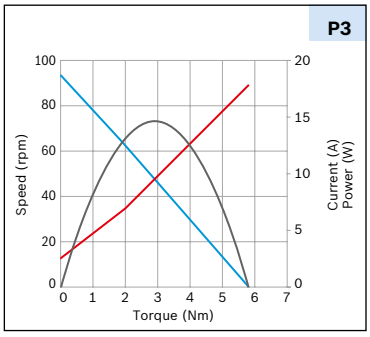

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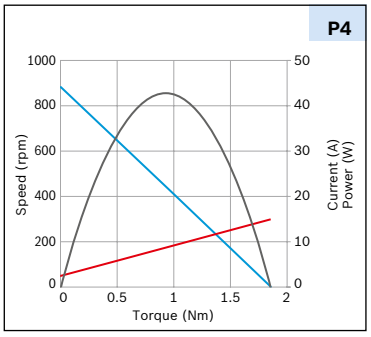
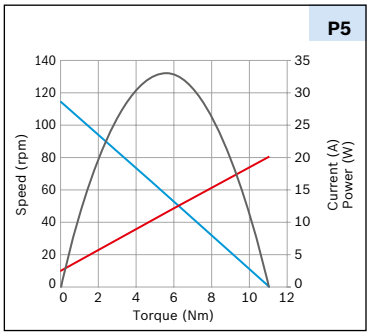


P5



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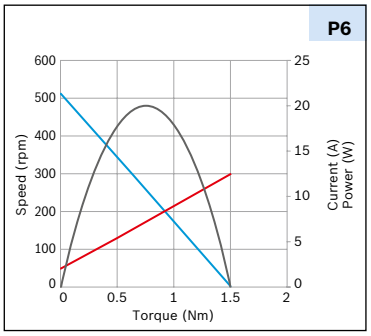

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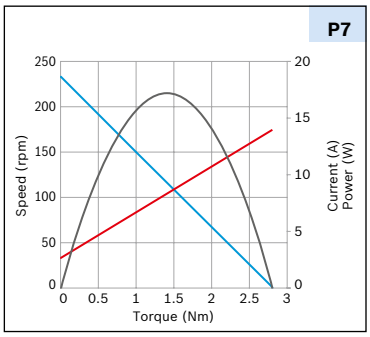
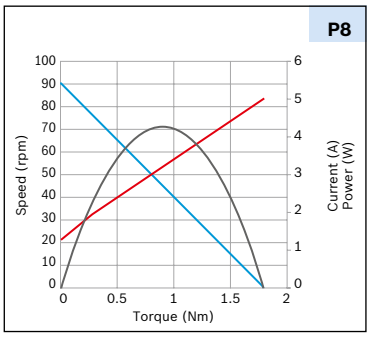


P8



AHC2

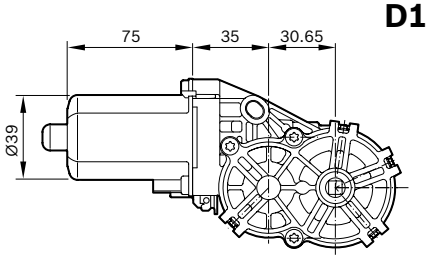
Family features:

- With and without hall sensor
- Degree of protection: IP 50
- Operation mode: S2
- Direction of rotation: CCW/CW

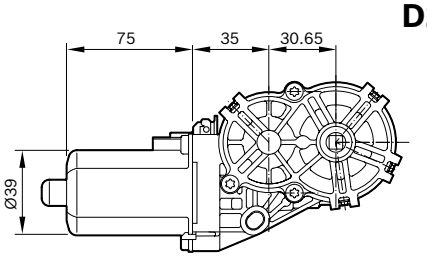
Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Signal	Side*	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm		Hall						
12 V	0 390 203 228	3.9	2.8	37.3	1	10.35	182:2	No	R	D1	W5	S1	C1	P4
	0 390 201 972	4.7	4	22.5	2	19	185.5:1	Yes	R	D3	W6	S1	C2	P2
	0 390 201 973	4.7	4	22.5	2	19	185.5:1	No	R	D3	W1	S1	C2	P2
	0 390 201 944	6	6	28.5	2	20	185.5:1	No	R	D1	W7	S4	C1	P1
	0 390 201 999	4.7	4	22.5	2	19	185.5:1	No	R	D3	W2	S1	C2	P2
	0 390 203 224	3.9	3.7	18.65	2	21.5	217:1	No	R	D3	W3	S2	C1	P3
	0 390 203 225	3.9	3.7	18.65	2	21.5	217:1	No	L	D4	W3	S2	C1	P3
	0 390 203 226	3.9	3.7	18.65	2	21.5	217:1	Yes	R	D3	W4	S2	C3	P3
	0 390 203 227	3.9	3.7	18.65	2	21.5	217:1	Yes	L	D4	W4	S2	C3	P3
	0 390 201 950	6.1	6	29	2	20.5	185.5:1	No	R	D1	W3	S3	C1	P1
	0 390 203 266	3.5	4.2	22.25	1.5	23	185.5:1	No	R	D1	W3	S1	C1	P5
	0 390 201 949	2.5	3.6	23.6	1	14.5	185.5:1	No	R	D1	W3	S1	C1	P7
	0 390 203 306	3.9	3.7	18.65	2	23.9	217:1	No	R	D3	W3	S5	C1	P8
	0 390 203 307	3.9	3.7	18.65	2	23.9	217:1	No	L	D4	W3	S5	C1	P3
	0 390 203 308	3.9	3.7	18.65	2	23.9	217:1	Yes	R	D3	W4	S5	C3	P3
	0 390 203 309	3.9	3.7	18.65	2	23.9	217:1	Yes	L	D4	W4	S5	C3	P3
	0 390 203 372	1.5	1.8	14.1	1	27.5	217:1	Yes	R	D3	W10	S2	C4	P9
24 V	0 390 203 310	3.5	2	16.9	2	23.3	217:1	No	R	D3	W8	S3	C1	P6
	0 390 203 311	3.5	2	16.9	2	23.3	217:1	No	L	D4	W8	S3	C1	P6
	0 390 203 312	3.5	2	16.9	2	23.3	217:1	Yes	R	D3	W9	S3	C3	P6
	0 390 203 313	3.5	2	16.9	2	23.3	217:1	Yes	L	D4	W9	S3	C3	P6

*Gear housing left: L, gear housing right: R

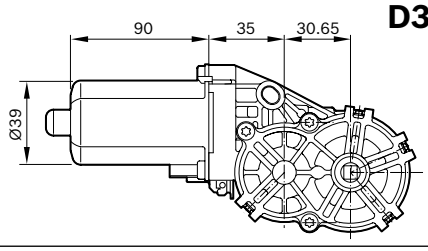
D1



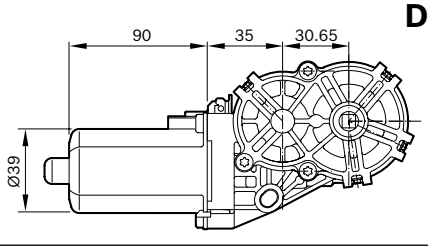
D2



D3

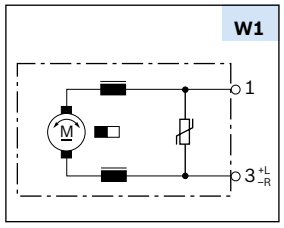


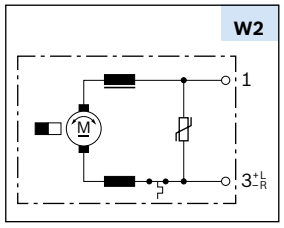
D4

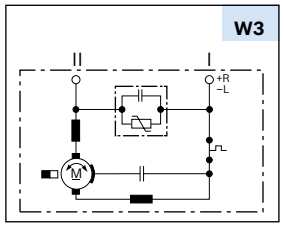


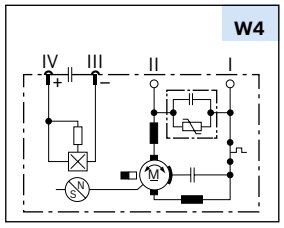
AHC2

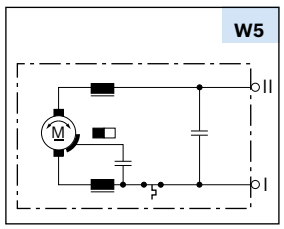
Wiring diagram (W)

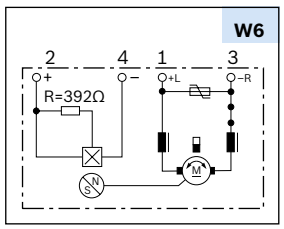


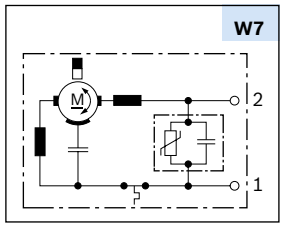


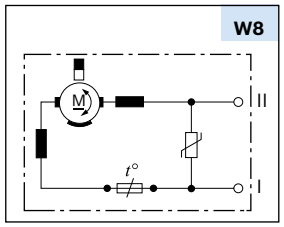


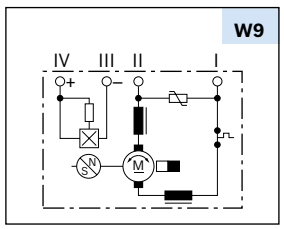


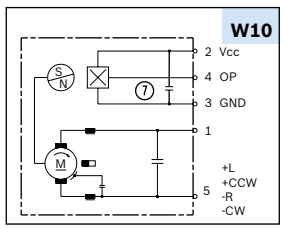




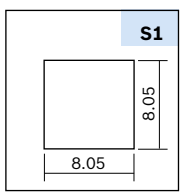


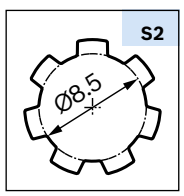


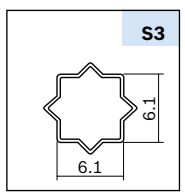


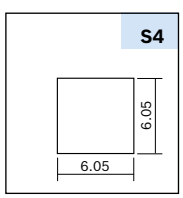


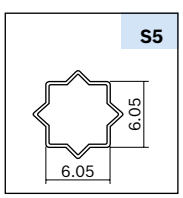
Drive end (S)



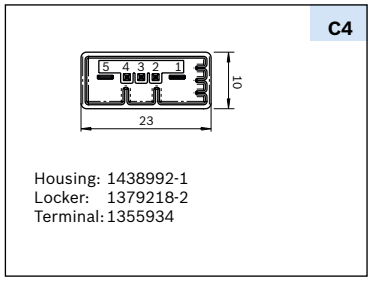




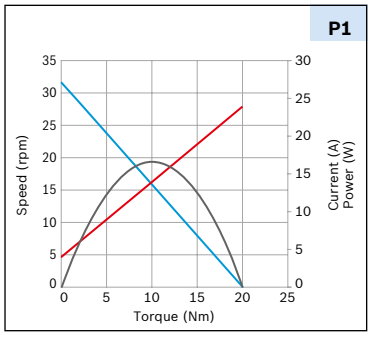


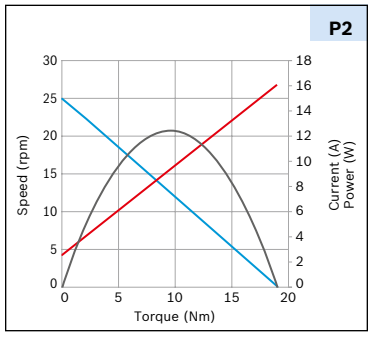


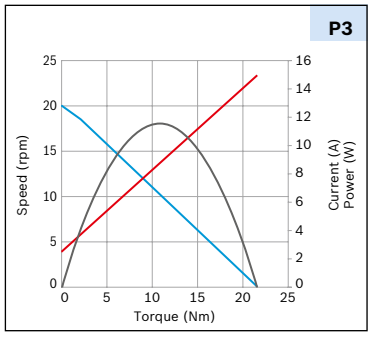
Mating connector (C)

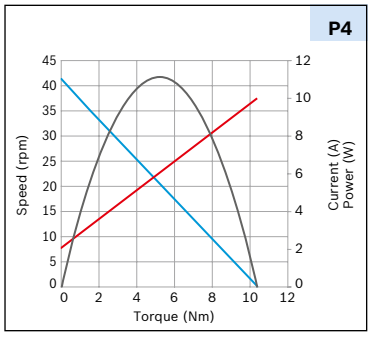


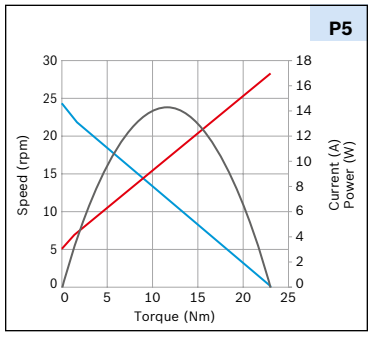
Performance curve (P)

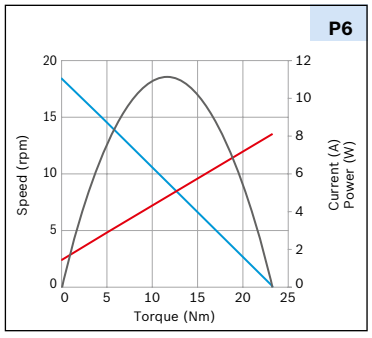


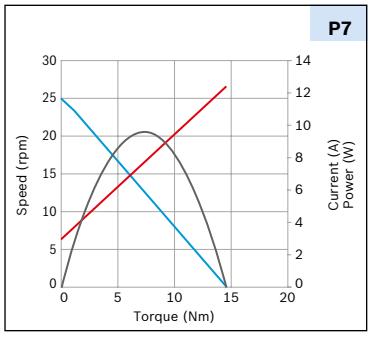


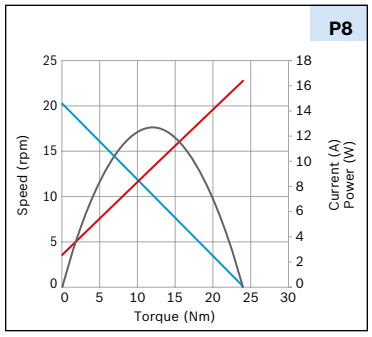


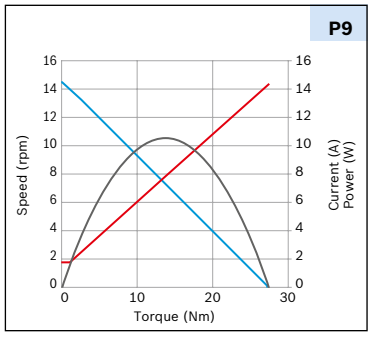












FPG2

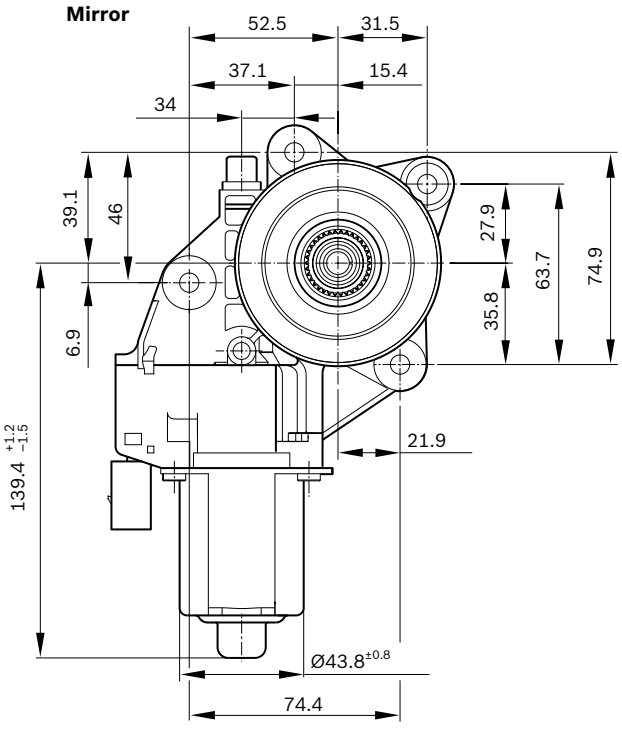
Family features:

- Double-hall sensor available
- Degree of protection: IP 54
- Operating mode: S2
- Direction of rotation: CCW/CW

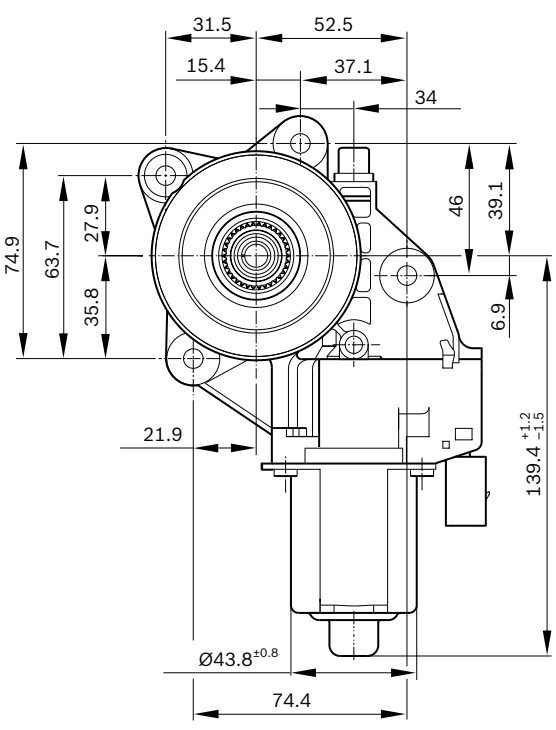
Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Signal	Side*	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm		Hall						
12 V	0 130 822 488	7.8	6	74.5	1	13.7	73:1	No	R	D1	W1	S1	C1	P1
	0 130 822 489	7.8	6	74.5	1	13.7	73:1	No	L	D2	W1	S1	C1	P1
	0 130 822 492	7.8	6	74.5	1	13	73:1	2x	R	D1	W1 + W3	S1	C2	P3
	0 130 822 493	7.8	6	74.5	1	13	73:1	2x	L	D2	W1 + W3	S1	C2	P3
24 V	0 130 822 490	8.2	3	78.5	1	13.7	73:1	No	R	D1	W2	S1	C1	P2
	0 130 822 494	8.2	3	78.5	1	13.7	73:1	2x	R	D1	W3	S1	C2	P2
	0 130 822 495	8.2	3	78.5	1	13.7	73:1	2x	L	D2	W3	S1	C2	P2

*Gear housing left: L, gear housing right: R

D1



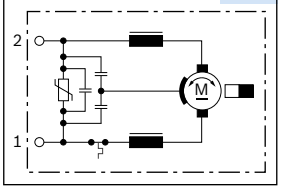
D2



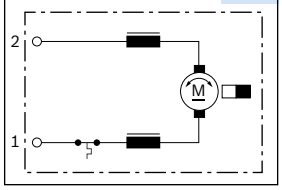
FPG2

Wiring diagram (W)

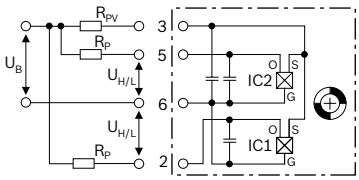
W1



W2

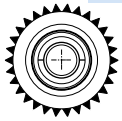


W3



Drive end (S)

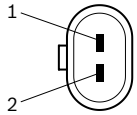
S1



DIN5481 - 21x24

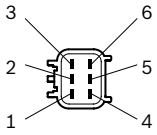
Mating connector (C)

C1



Housing: Lear 16694.627.626 / TE 493989-1
Locker: –
Terminal: LEAR MDK 3 PLUS 26628.331.179

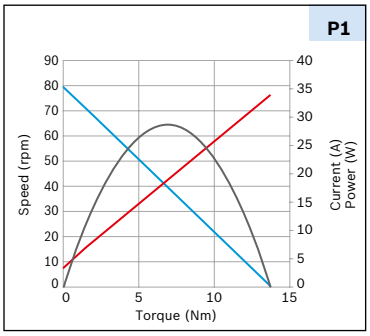
C2



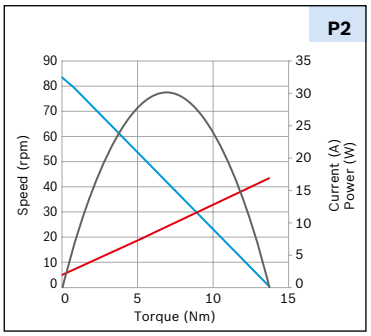
Housing: Yazaki 7287-1116-30
Locker: –
Terminal: LEAR MDK 3 PLUS 26628.331.179

Performance curve (P)

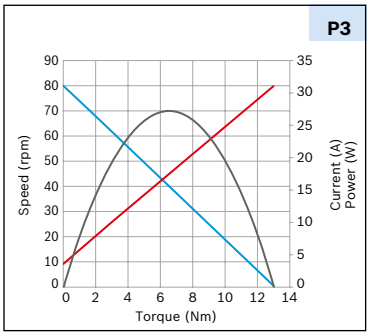
P1



P2



P3



FPG EVO

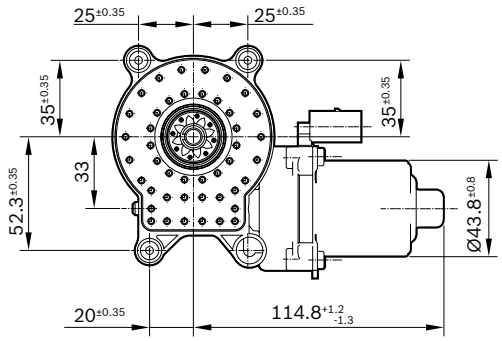
Family features:

- Ripple function
- Degree of protection: IP 5X
- Operation mode: S2 – 5min
- Direction of rotation: CCW/CW

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Signal	Side*	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm		ripple						
12 V	F 006 B40 702	8.6	6	82	1	10	73:1	Yes	R	D1	W1	S1	C1	P1
	F 006 B40 703	8.6	6	82	1	10	73:1	Yes	L	D2	W1	S1	C1	P1
	F 006 B49 680	8.6	6	82	1	10	73:1	Yes	R	D1	W2	S2	C1	P1
	F 006 B49 681	8.6	6	82	1	10	73:1	Yes	L	D2	W2	S2	C1	P1
	F 006 B49 780	8.6	6	82	1	10	73:1	Yes	R	D1	W2	S3	C1	P1
	F 006 B49 781	8.6	6	82	1	10	73:1	Yes	L	D2	W2	S3	C1	P1

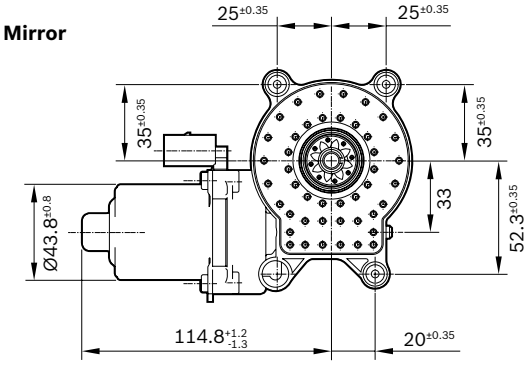
*Gear housing left: L, gear housing right: R

D1



D2

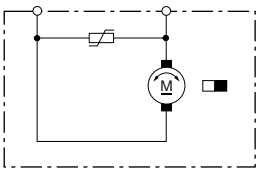
Mirror



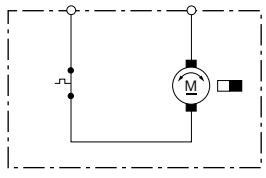
FPG EVO

Wiring diagram (W)

W1

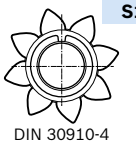


W2



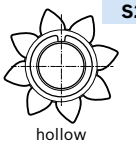
Drive end (S)

S1



DIN 30910-4
SINT D39

S2



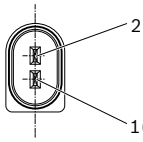
hollow
DIN EN 10277-3

S3

DIN 30910-4
SINT D39

Mating connector (C)

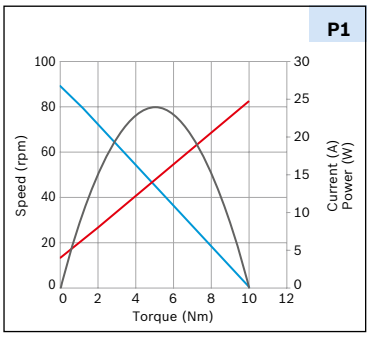
C1



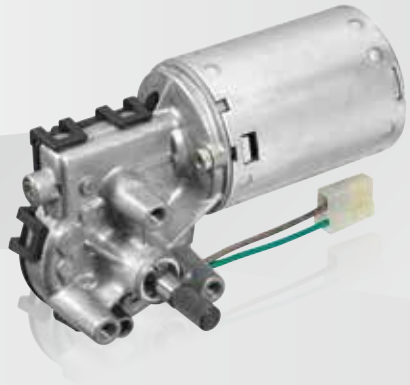
Housing: TE 493989-1
Locker: –
Terminal: LEAR MDK 3 PLUS 26628.331.179

Performance curve (P)

P1



CHP



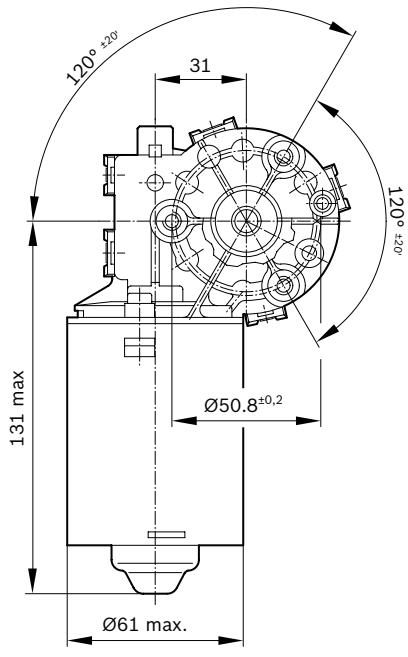
Family features:

- Degree of protetion: IP 23
- Operation mode: S1
- Direction of rotation: CCW/CW

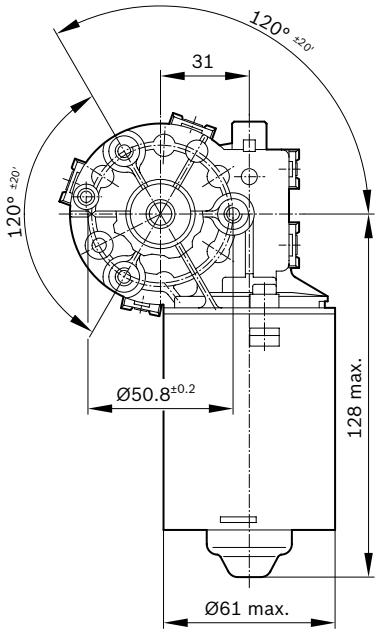
Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque	Ma (Stall torque)	Gear ratio	Signal	Side*	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm		Hall						
12 V	F 006 B20 093	28.1	9	167.5	1.6	16	52:2	No	R	D1	W3	S1	C1	P1
	F 006 B20 092	20.7	4.5	44	4.5	27	69:1	No	L	D2	W2	S2	–	P7
24 V	F 006 B20 103	18.8	3.1	180	1	10	52:2	No	R	D1	W3	S1	C1	P9
	F 006 B20 101	11.3	2	108	1	18	52:2	No	L	D3	W3	S6	C1	P3
	F 006 B20 102	41.9	5.5	160	2.5	12	52:2	No	R	D1	W4	S5	C1	P6
	F 006 B20 099	13.1	2.5	125	1	15	52:2	No	L	D3	W3	S5	C1	P4
	F 006 B20 100	13.1	2.5	125	1	15	52:2	No	R	D1	W3	S5	C1	P4
	F 006 B20 095	7.7	3.5	49	1.5	15	55:1	No	R	D1	W4	S7	–	P5
	F 006 B20 096	9.7	1.5	37	2.5	27	55:1	No	L	D2	W1	S3	C1	P8
	F 006 B20 179	11.3	2	108	1	18	52:2	No	L	D3	W3	S6	C1	P11
	F 006 B20 097	16.7	5.3	66.5	2.4	24	69:1	No	L	D3	W3	S3	–	P2
	F 006 B20 098	13.6	4	54	2.4	24	55:1	No	L	D3	W3	S4	C1	P10

*Gear housing left: L, gear housing right: R

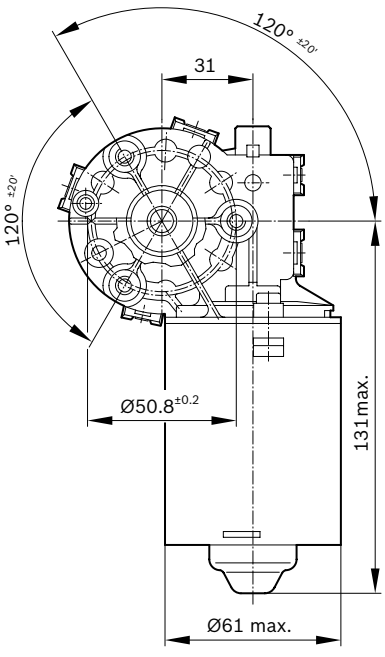
D1



D2



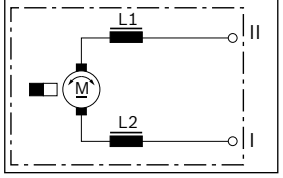
D3



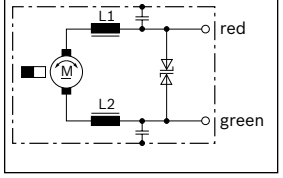
CHP

Wiring diagram (W)

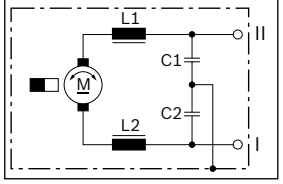
W1



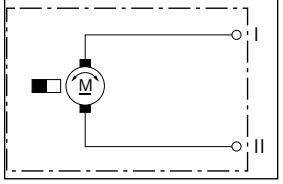
W2



W3



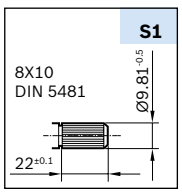
W4



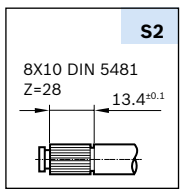
I = green
II = brown or red

Drive end (S)

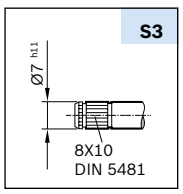
S1



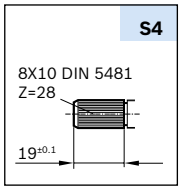
S2



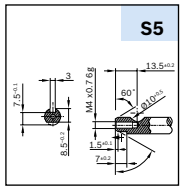
S3



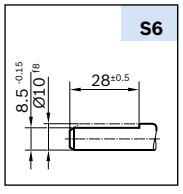
S4



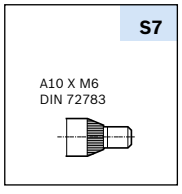
S5



S6

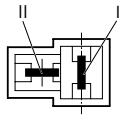


S7



Mating connector (C)

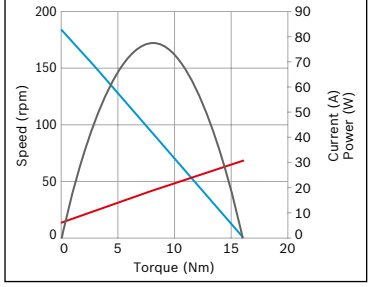
C1



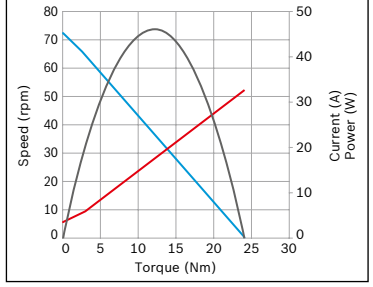
Housing: DIN 46 340 – B6,3-MS
Locker: –
Terminal: TE160859-1
Pins: AMD 180 907 0d.926 474-1

Performance curve (P)

P1



P2



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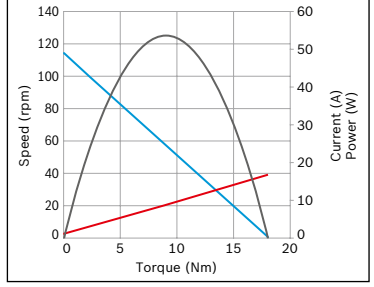
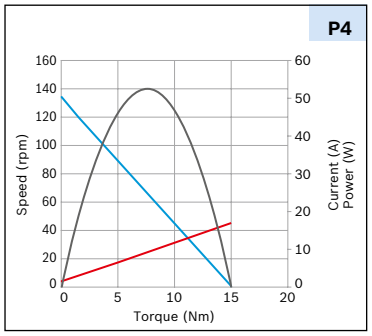
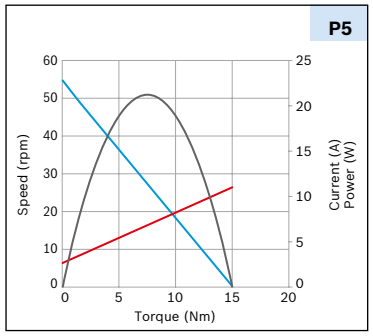


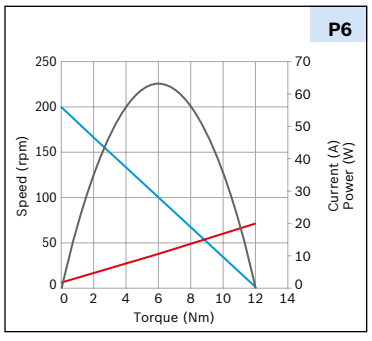
P4



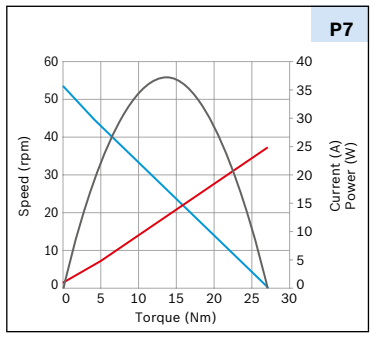
P5



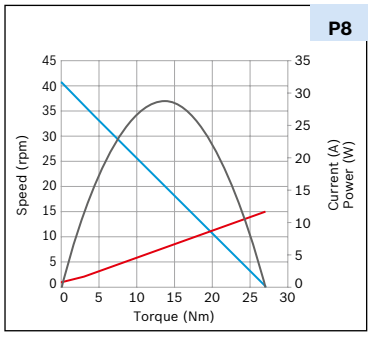
P6



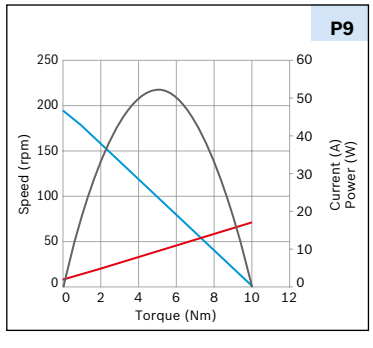
P7



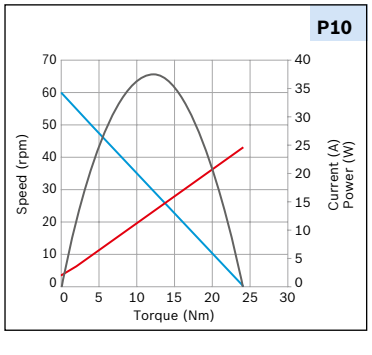
P8



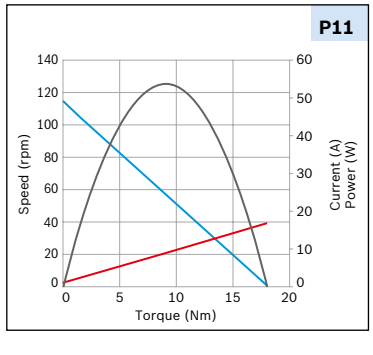
P9



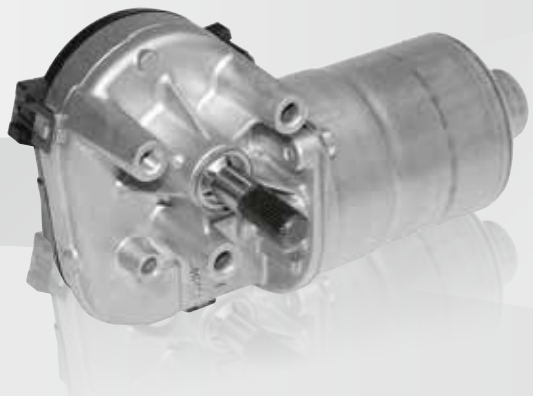
P10



P11



CHP3



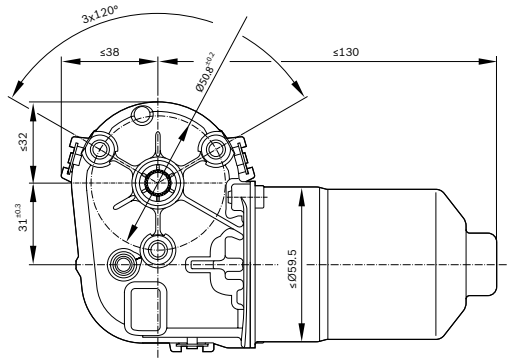
Family features:

- Double-Hall sensor available
- Degree of protection: IP 23
- Operation mode: S2/S3
- Dual-speed motors available

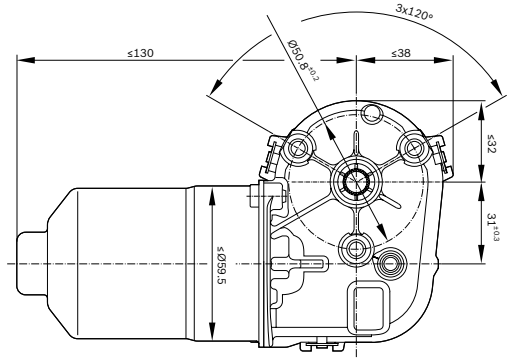
Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Direction of rotation	Signal	Side*	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm			Hall						
12 V	0 390 243 610	12.8 / 8.5	4.5 / 3.5	61 / 40.5	2	30 / 35	76:1	CW	No	R	D3	W3	S2	C3	P2
	0 390 243 611	12.8 / 8.5	4.5 / 3.5	61 / 40.5	2	30 / 35	76:1	CCW	No	L	D4	W3	S2	C3	P2
24 V	F 006 B20 410	28.8	3.75	55	5	32	88:1	CCW/CW	2x	R	D1	W2	S1	C1	P1
	F 006 B20 411	28.8	3.75	55	5	32	88:1	CCW/CW	No	R	D1	W1	S1	C2	P1
	F 006 B20 412	28.8	3.75	55	5	32	88:1	CCW/CW	2x	L	D2	W2	S1	C1	P1
	F 006 B20 413	28.8	3.75	55	5	32	88:1	CCW/CW	No	L	D2	W1	S1	C2	P1

*Gear housing left: L, gear housing right: R

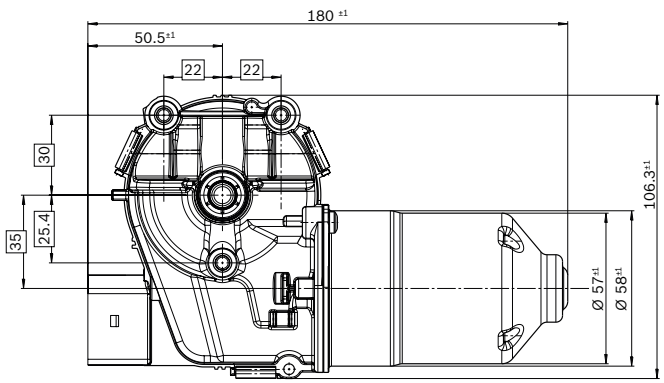
D1



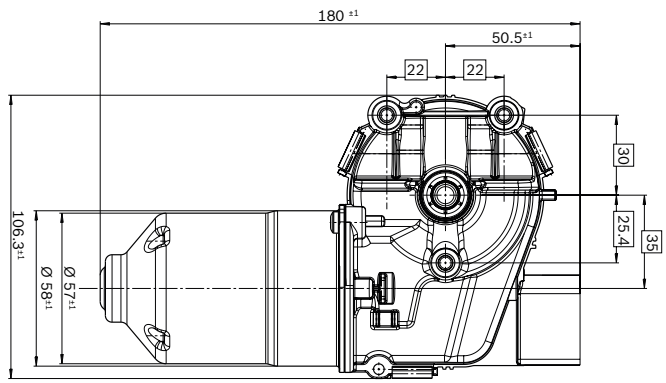
D2



D3



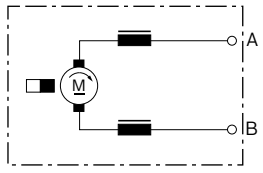
D4



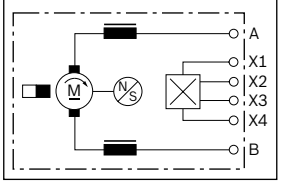
CHP3

Wiring diagram (W)

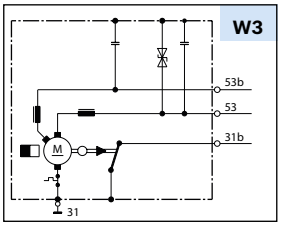
W1



W2

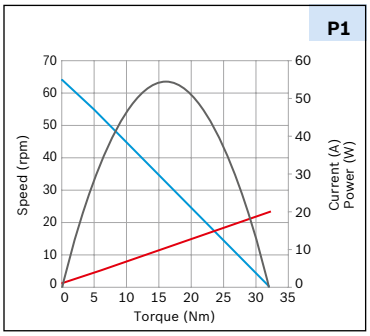


W3

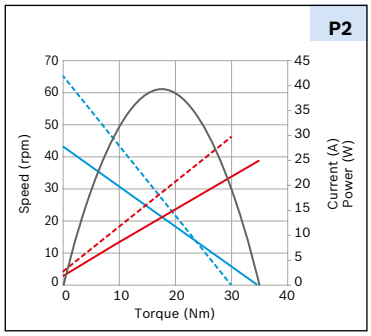


Performance curve (P)

P1

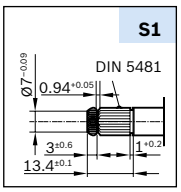


P2

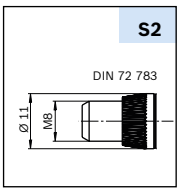


Drive end (S)

S1

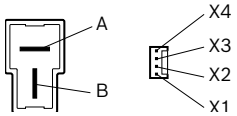


S2



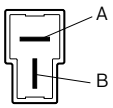
Mating connector (C)

C1



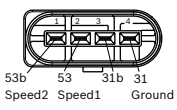
Housing: TE 18098
Locker: –
Terminal: TE160859-1

C2



Housing: TE 18098
Locker: –
Terminal: TE160859-1

C3



Housing: 0390Y01503
Locker: –
Terminal:

CEP

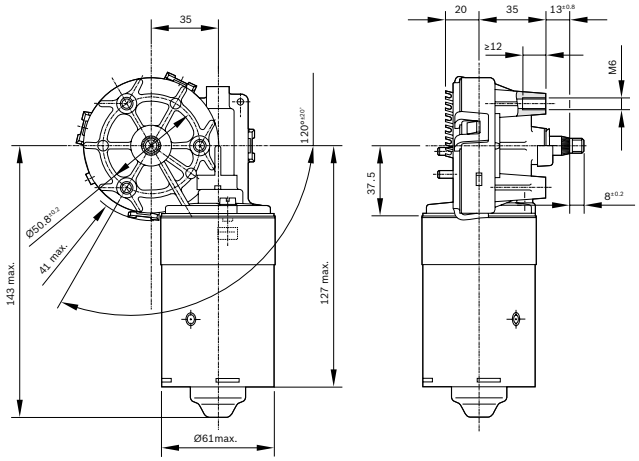
Family features:

- With and without hall sensor
- Operation mode: S1
- Dual-speed motors available

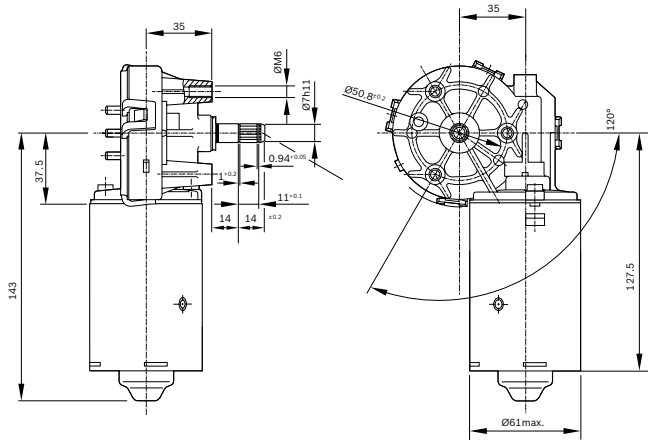
Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Direction of rotation	Signal	Side**	Degree of Protection (IP)	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm			Hall							
12 V	F 006 B20 145*	6.7 ; 10.4	3.5 ; 5.5	32 ; 50	2	23 ; 20	63:1	CCW	No	L	IP53	D1	W1	S1	C1	P3
24 V	F 006 B20 048*	6.9 ; 10.7	2 ; 3	33 ; 51	2	30 ; 23	63:1	CCW	No	L	IP53	D1	W2	S1	C2	P1
	F 006 B20 064*	6.9 ; 10.7	2 ; 3	33 ; 51	2	30 ; 23	63:1	CCW	No	L	IP53	D1	W2	S1	–	P1
	F 006 B20 146*	6.9 ; 10.7	2 ; 3	33 ; 51	2	30 ; 23	63:1	CCW	No	L	IP53	D1	W1	S1	C1	P5
	F 006 B20 106	9.8	3.5	47	2	32.5	79:1	CCW/CW	No	L	IP23	D2	W3	S3	C3	P2
	F 006 B20 360	16	2.4	51	3	35	63:1	CCW/CW	Yes	R	IP23	D3	W5	S2	C4	P4
	F 006 WM0 310	16	2.4	51	3	35	63:1	CCW/CW	No	R	IP23	D3	W4	S2	–	P4

* Motors with two speeds / **gear housing left: L, gear housing right: R

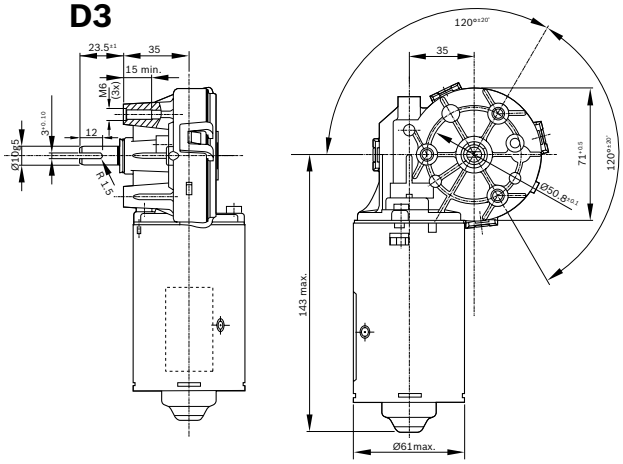
D1



D2



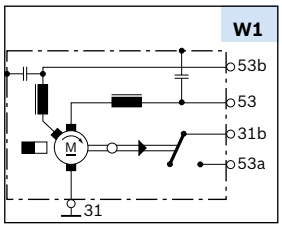
D3



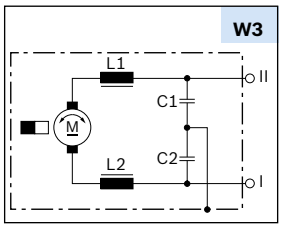
CEP

Wiring diagram (W)

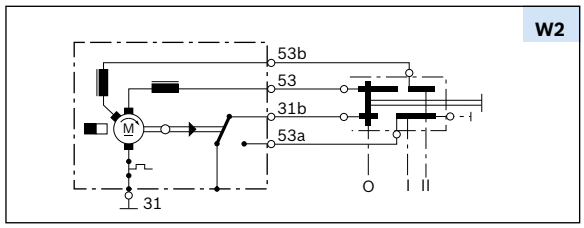
W1



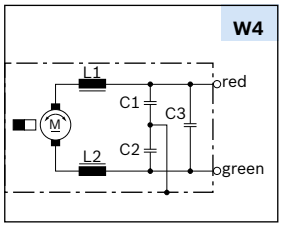
W3



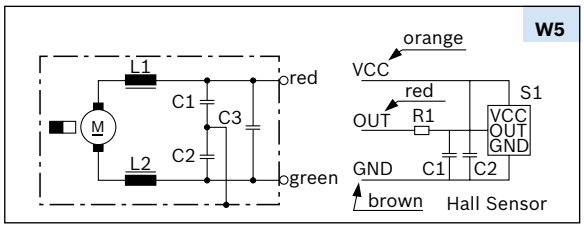
W2



W4

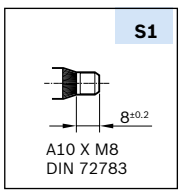


W5

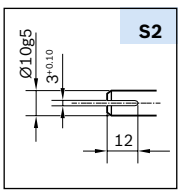


Drive end (S)

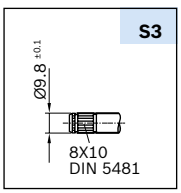
S1



S2

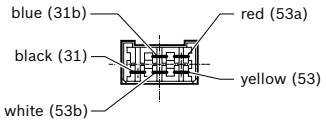


S3



Mating connector (C)

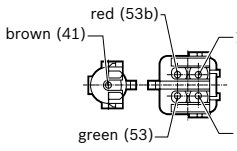
C1



Housing: TE 180904-0
Locker: –
Terminal: TE 160859-1

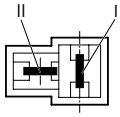
Mating connector (C)

C2



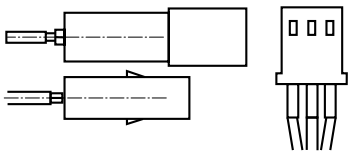
Housing: Delphi 12010996

C3



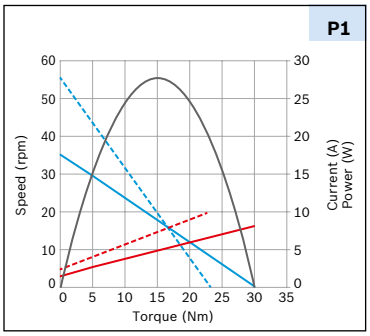
Housing: DIN 46 340 – B6,3-MS
Locker: –
Terminal: TE160859-1
Pins: AMD 180 907 0d.926 474-1

C4

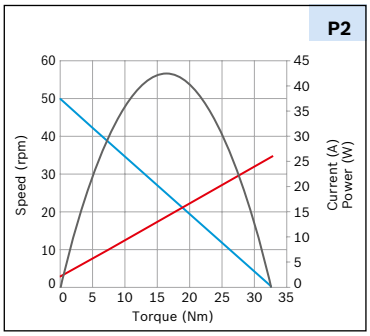


Performance curve (P)

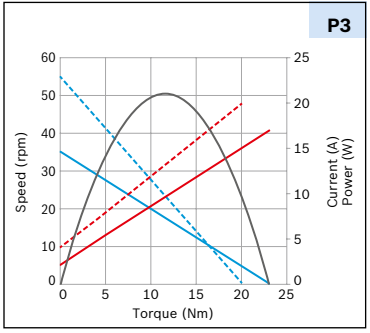
P1



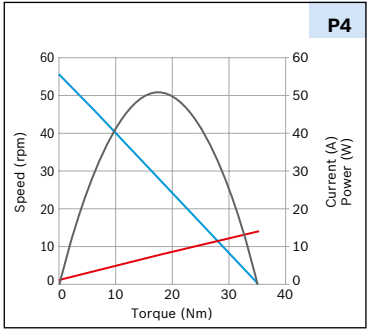
P2



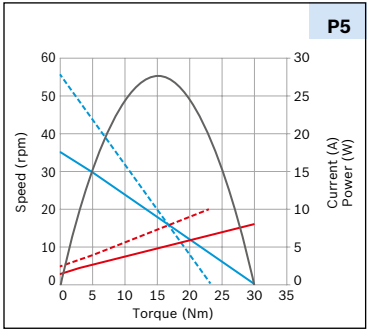
P3



P4



P5



CDP

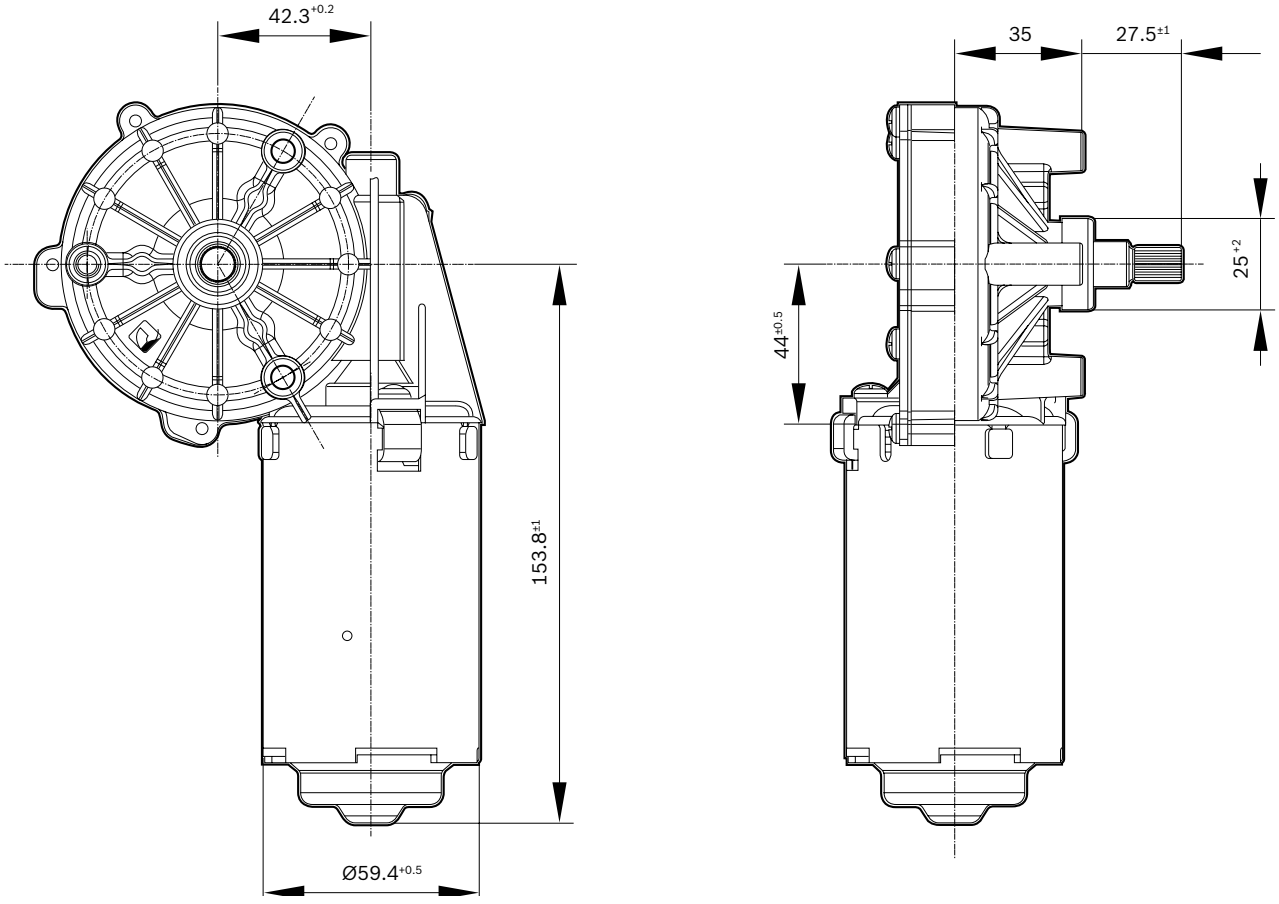
Family features:

- Also with wiper function available
- Hall sensor available
- Degree of protection: IP 50
- Operation mode: S1

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Direction of rotation	Signal	Side**	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm			Hall						
12 V	0 986 337 225*	14.7 ; 20.9	5.5 ; 8	35 ; 50	4	51 ; 39	2:108	CCW	No	L	D1	W1	S1	C1	P4
	0 986 337 270	50.2	10	42	10	45	2:108	CCW/CW	2x	L	D1	W2	S2	C2	P5
	0 986 337 280	38.7	8.5	37	10	40	1:78	CCW/CW	2x	L	D1	W2	S3	C2	P1
24 V	0 986 337 200*	8.5 ; 13.8	2.75 ; 3.75	27 ; 44	3	50 ; 46	1:78	CCW	No	L	D1	W1	S3	C1	P6
	0 986 337 201	20.9	3.5	40	5	30	2:108	CCW/CW	No	L	D1	W3	S2	–	P7
	0 986 337 209*	8.8 ; 14.4	3 ; 4	28 ; 46	3	50 ; 41	1:78	CCW	No	L	D1	W1	S1	C3	P3
	0 986 337 250	50.2	6	80	6	45	2:108	CCW/CW	2x	L	D1	W2	S2	C2	P2

* Motors with two speeds / **gear housing left: L, gear housing right: R

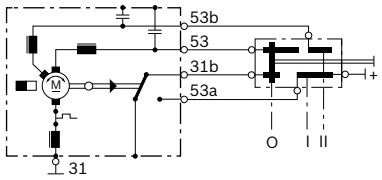
D1



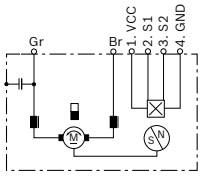
CDP

Wiring diagram (W)

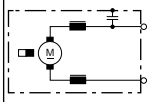
W1



W2

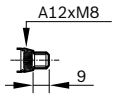


W3

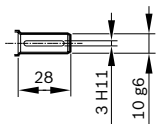


Drive end (S)

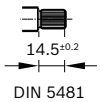
S1



S2

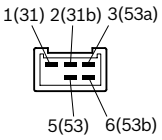


S3



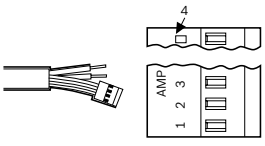
Mating connector (C)

C1



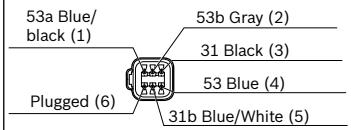
Housing: TE 180904-0
Locker: –
Terminal: TE 160927-2 for 1.5 - 2.5 mm² c

C2



Tyco 3-640441-4

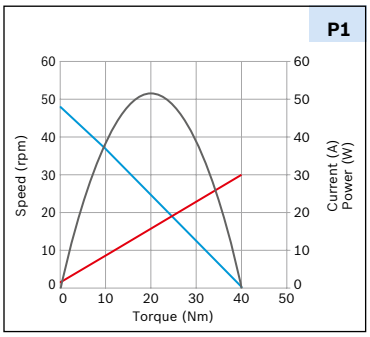
C3



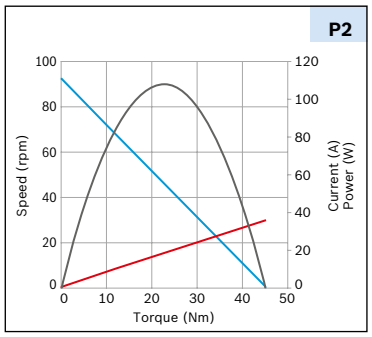
Junction block: DT04-6P

Performance curve (P)

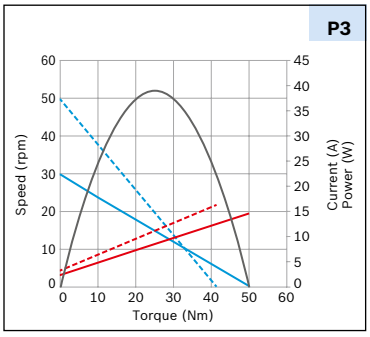
P1



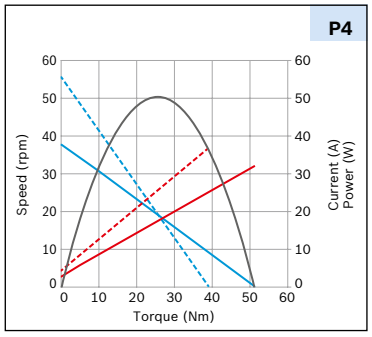
P2



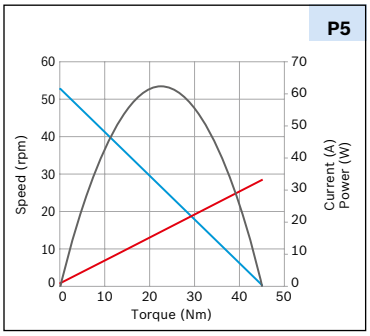
P3



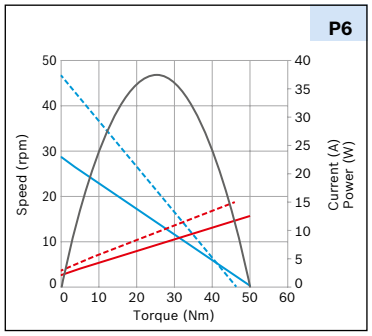
P4



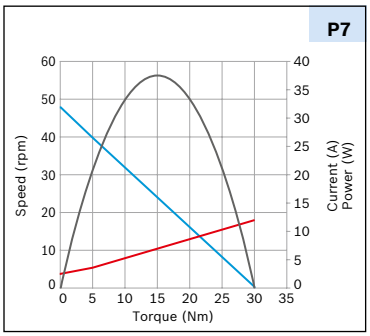
P5



P6



P7



EFP

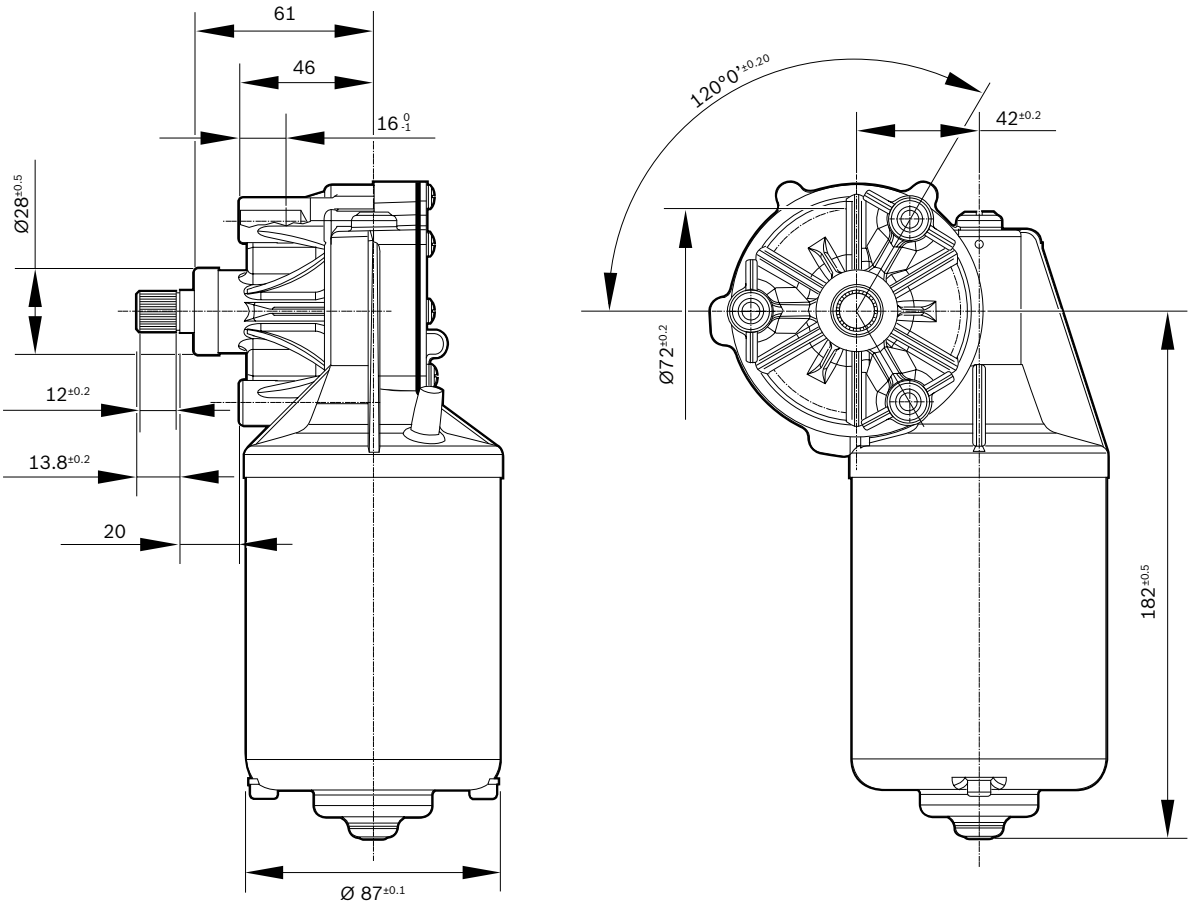
Family features:

- Also with wiper function available
- Degree of protection: IP 23
- Operating mode: S1

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Direction of rotation	Signal	Side**	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm			Hall						
12 V	0 986 337 400*	8.4 ; 12.5	4.5 ; 6	32 ; 48	2.5	45 ; 40	80:2	CCW	No	L	D1	W1	S1	C1	P4
	0 986 337 411	20.4	5	39	5	70	65:1	CCW/CW	No	L	D1	W2	S1	C2	P6
24 V	0 986 337 401*	9.7 ; 16.3	1.75 ; 2	31 ; 52	3	60 ; 50	80:2	CCW	No	L	D1	W1	S1	C1	P1
	0 986 337 402*	11.3 ; 18.4	2.25 ; 2.75	27 ; 44	4	70 ; 60	65:1	CCW	No	L	D1	W1	S1	C1	P3
	0 986 337 409	65.9	6	63	10	60	80:2	CCW/CW	No	L	D1	W2	S2	C2	P2
	0 986 337 410	73.3	7	70	10	60	80:2	CCW/CW	No	L	D1	W2	S2	C2	P5

* Motors with two speeds / **gear housing left: L, gear housing right: R

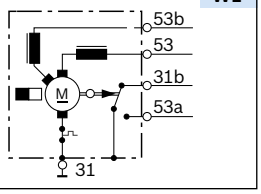
D1



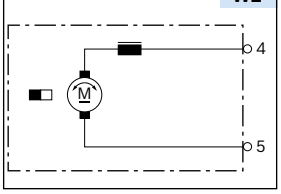
EFP

Wiring diagram (W)

W1

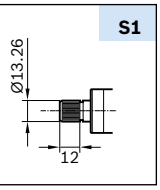


W2

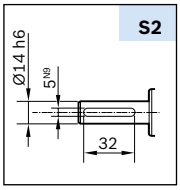


Drive end (S)

S1

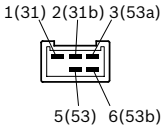


S2



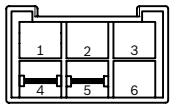
Mating connector (C)

C1



Housing: TE 180904-0
Locker: –
Terminal: TE 160927-2 for 1.5 - 2.5 mm² c

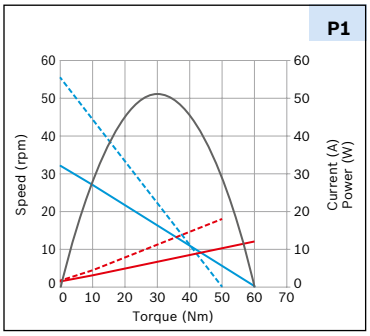
C2



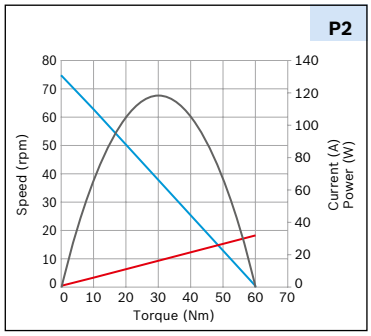
C–180906
1: not connected
2: not connected
3: not connected
4: First speed (Green)
5: Minus (Black)
6: not connected

Performance curve (P)

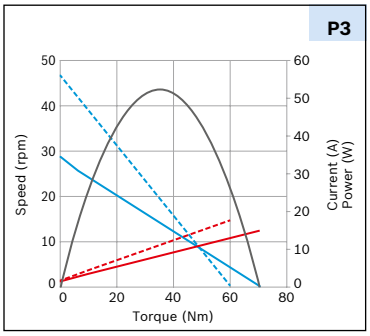
P1



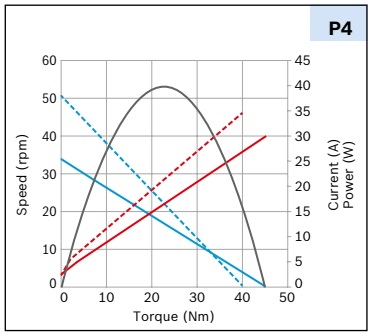
P2



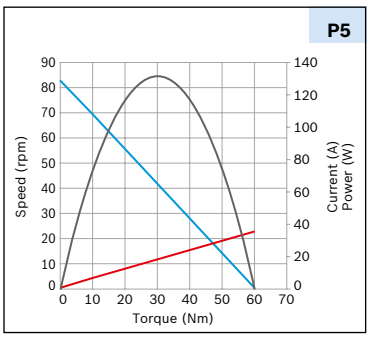
P3



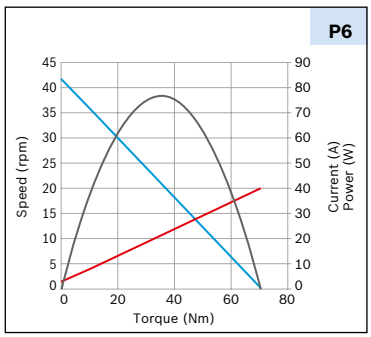
P4



P5



P6



EDP

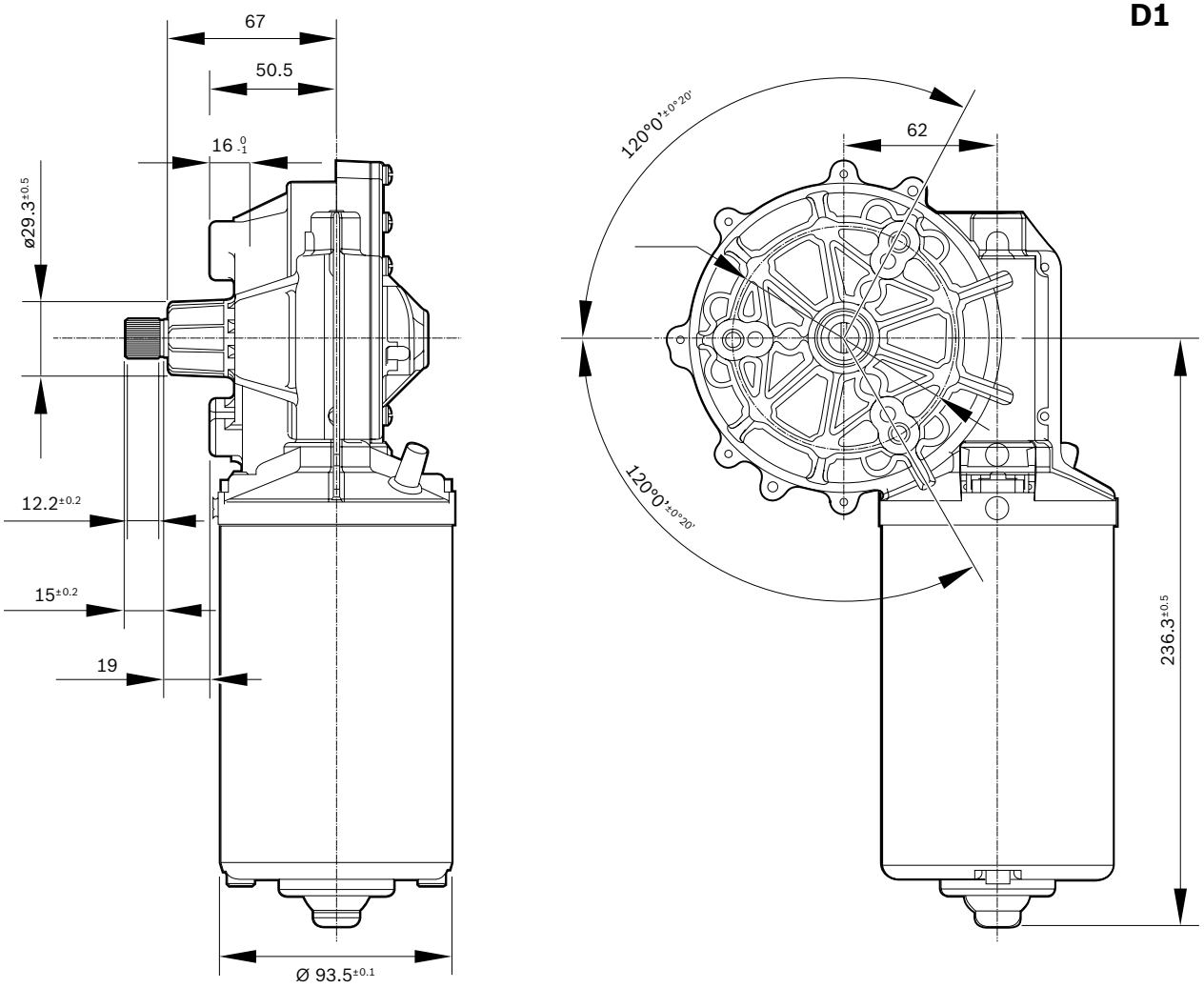
Family features:

- Powerful 2-speed motor
- Degree of protection: IP 23
- Operating mode: S1
- Direction of rotation: CCW

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Direction of rotation	Signal	Side*	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm			Hall						
24 V	0 986 337 451	19.3 ; 33.5	3.5 ; 6	23 ; 40	8	120 ; 80	96:2	CCW	No	L	D1	W1	S1	C1	P1

*Gear housing left: L, gear housing right: R

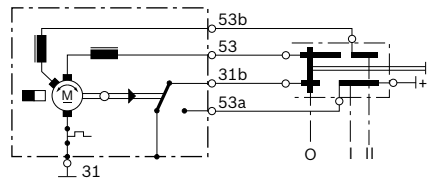
D1



EDP

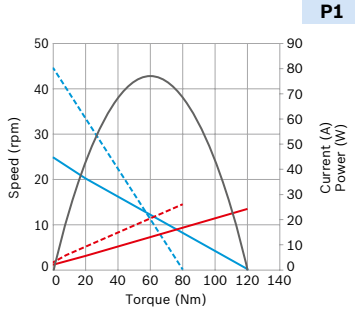
Wiring diagram (W)

W1



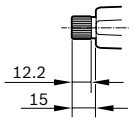
Performance curve (P)

P1



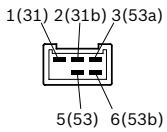
Drive end (S)

S1



Mating connector (C)

C1



Housing: TE 180904-0
Locker: –
Terminal: TE 160927-2 for 1.5 - 2.5 mm² c

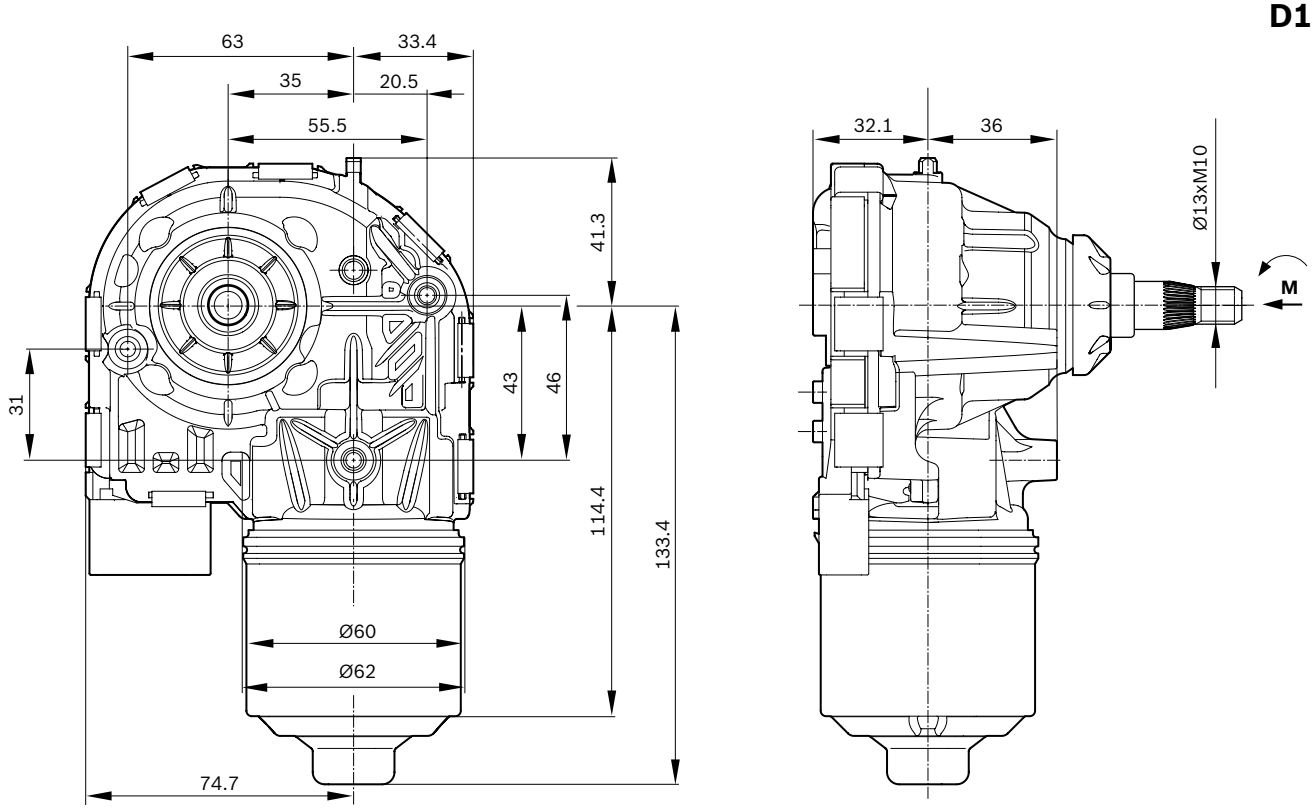
WDD

Family features:

- Motor with integrated electronics
- Degree of protection: IP 6K7
- Operating mode: S1
- Direction of rotation: CCW/CW
- LIN Communication

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Gear ratio	Signal	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm		LIN					
12 V	0 390 248 015	30	4.5	50	5.7	38	76:1	Yes	D1	W1	S1	C1	P1
	0 390 248 016	30	4.5	50	5.7	38	76:1	Yes	D1	W1	S2	C1	P1

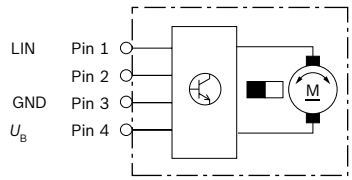
D1



WDD

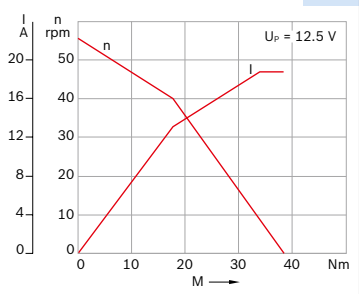
Wiring diagram (W)

W1



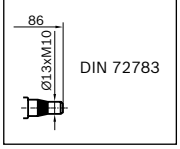
Performance curve (P)

P1

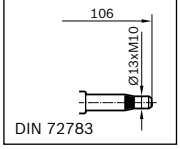


Drive end (S)

S1

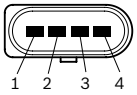


S2



Mating connector (C)

C1



Housing: TE 180904-0
Locker: –
Terminal: TE 160927-2 for 1.5 - 2.5 mm² c

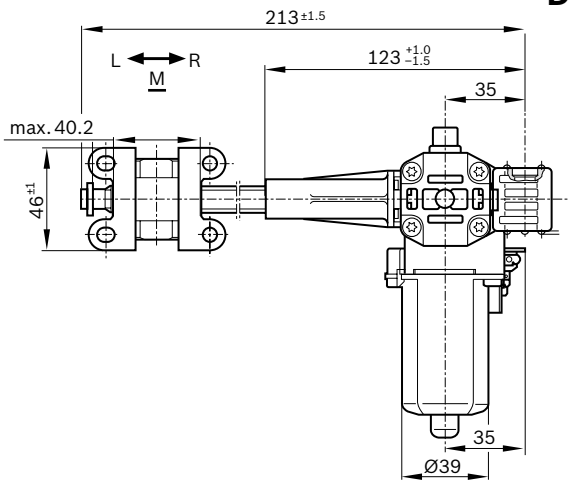
AHC-RS

Family features:

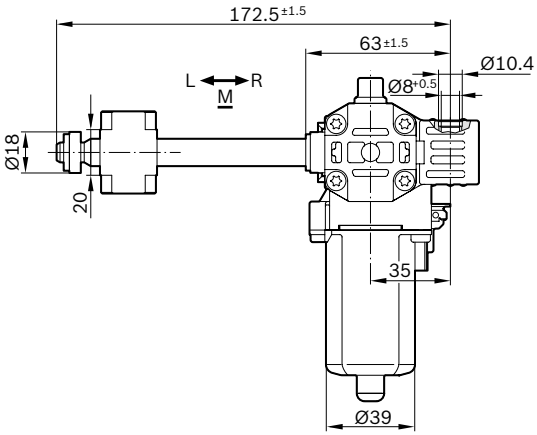
- Hall Sensor available
- Degree of protection: IP 50
- Operation mode: S2 - S3
- Linear movement

Voltage	Part number	In (Nominal current)	Fn (Nominal force)	Fmax Maximun force	Adjustment speed	Stroke	Signal	Dimensional drawing (D)	Wiring diagram (W)	Connector (C)	Performance curve (P)
		A	kN	kN	mm/s	mm	Hall				
12 V	0 390 203 229	9	0.5	3	13	81.6	Yes	D3	W1	C3	P3
	0 390 201 927	3	0.5	3.4	5.2	58.5	Yes	D1	W2	C1	P1
	0 390 201 941	3.9	0.5	4.5	7.2	75	No	D2	W3	C2	P2
	0 390 201 989	6	0.5	4.25	7	58.5	Yes	D4	W1	C3	P4

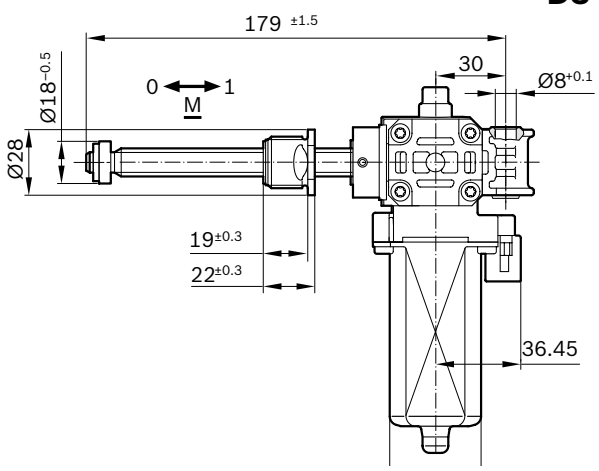
D1



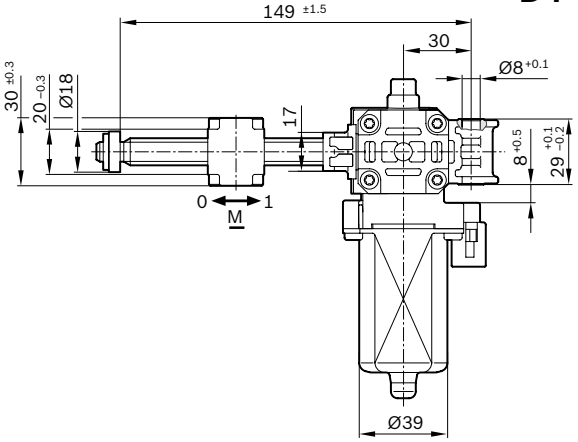
D2



D3



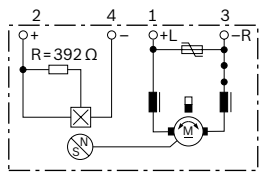
D4



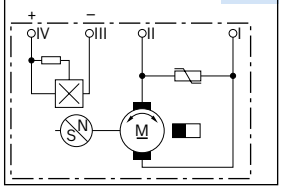
AHC-RS

Wiring diagram (W)

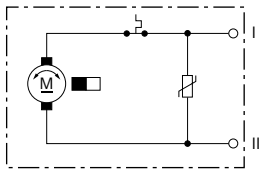
W1



W2

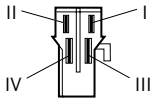


W3



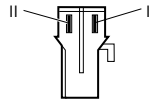
Mating connector (C)

C1



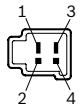
Housing: TE 968182-1
Locker: TE 0-968183-1
Terminal: TE JPT 0-927768-1 /
MTIII 0-968052-1 (x2)

C2



Housing: TE 968182-1
Locker: TE 0-968183-1
Terminal: TE JPT 0-927768-1 (x2)

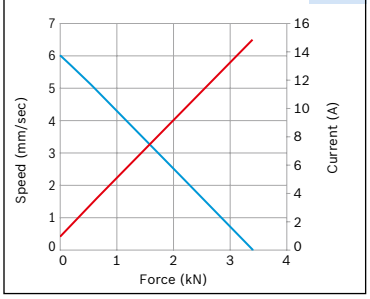
C3



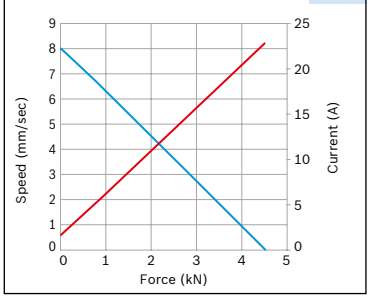
Housing: FCI 3 023 59 01
Locker: –
Terminal: TE MQS PIN Contact 6-928918-1
Pin 0.63 x 0.63 mm / TE MPQ
Pin 2.8 x 0.63 968137-2 2.80 mm

Performance curve (P)

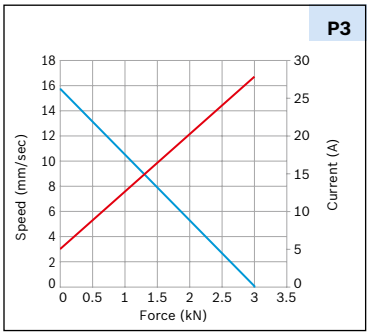
P1



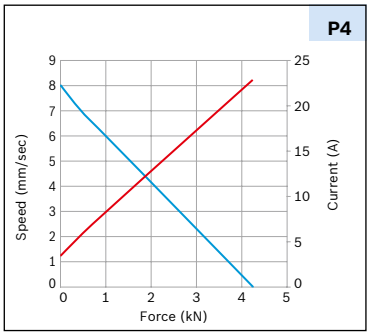
P2



P3



P4



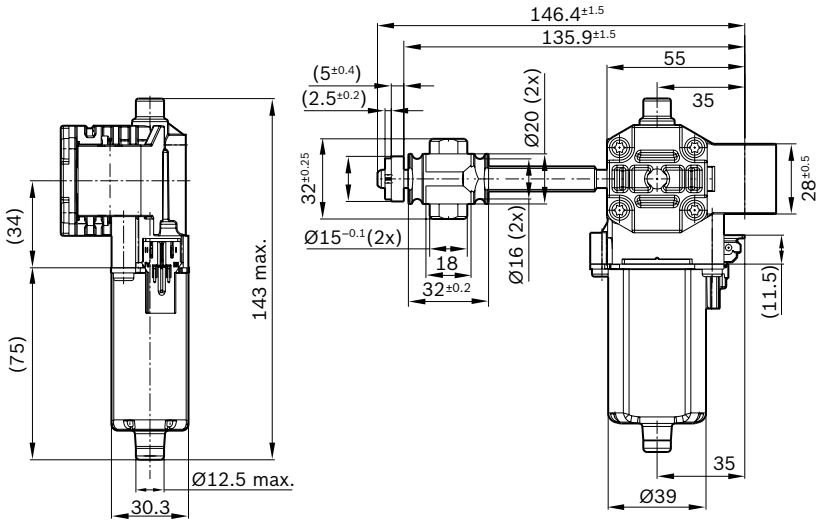
AHC-RS2

Family features:

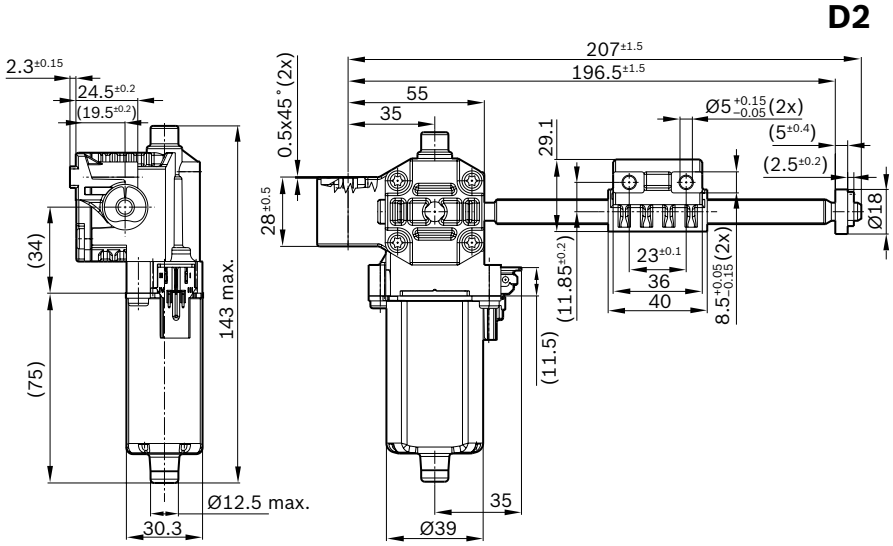
- Hall Sensor available
- Degree of protection: IP 50
- Operation mode: S2 - S3
- Linear movement

Voltage	Part number	In (Nominal current)	Fn (Nominal force)	Fmax Maximun force	Adjustment speed	Stroke	Signal	Dimensional drawing (D)	Wiring diagram (W)	Connector (C)	Performance curve (P)
		A	kN	kN	mm/s	mm	Hall				
12 V	0 390 203 693	10	0.4	1.95	15	48.9	Yes	D1	W1	C1	P1
	0 390 203 694	8	0.4	2.07	13	101.5	Yes	D2	W1	C1	P2

D1



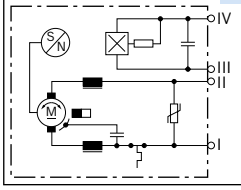
D2



AHC-RS2

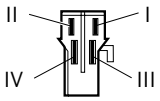
Wiring diagram (W)

W1



Mating connector (C)

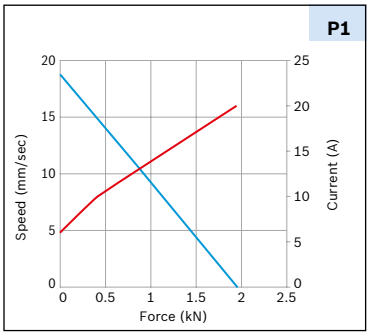
C1



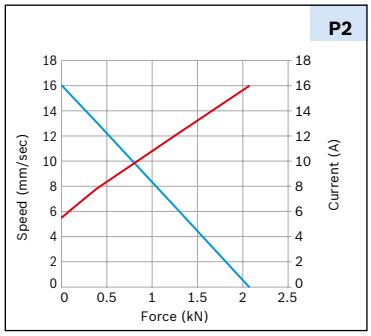
Housing: TE 968182-1
Locker: TE 0-968183-1
Terminal: TE JPT 0-927768-1 / MTIII
0-968052-1 (x2)

Performance curve (P)

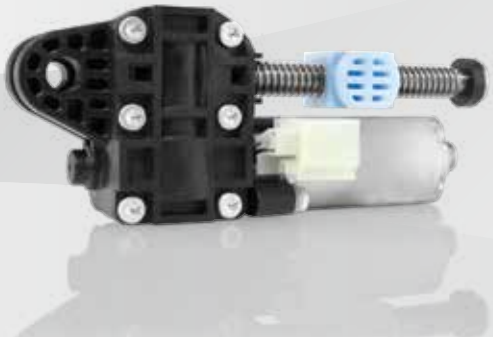
P1



P2



AHC-D



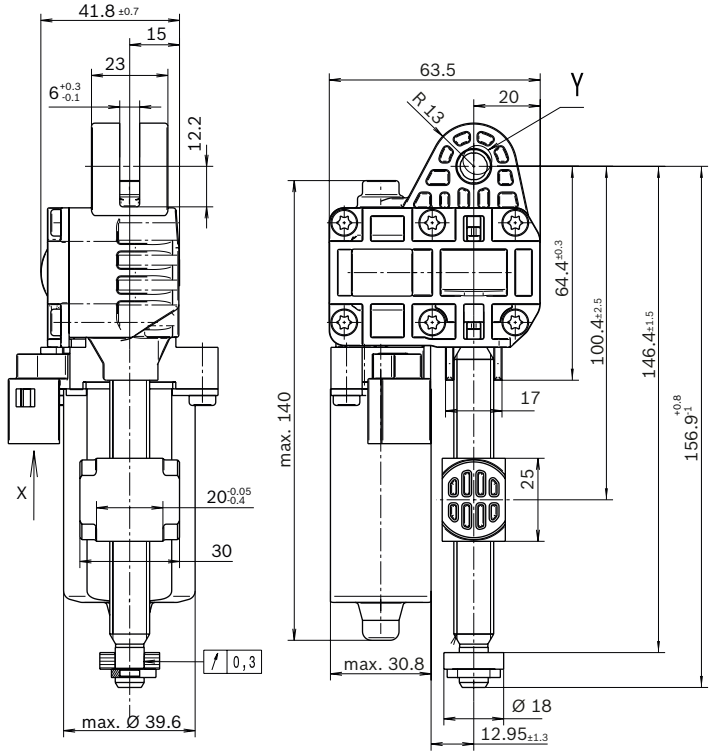
Family features:

- Hall Sensor available
- Degree of protection: IP 50
- Operation mode: S2 - S3
- Linear movement

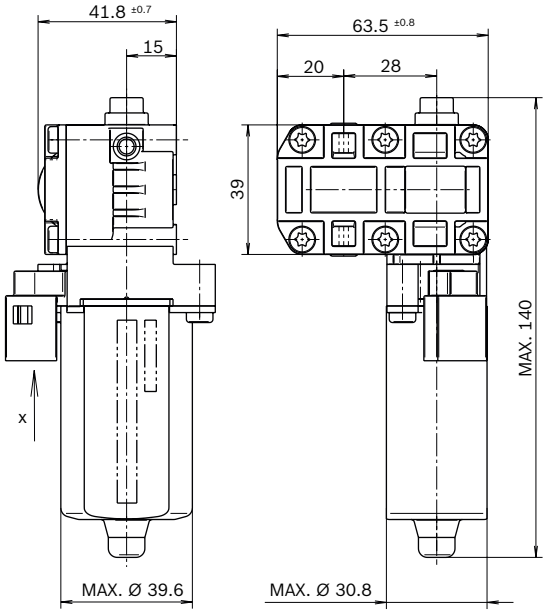
Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Gear ratio	Signal	Direction of rotation	Dimensional drawing (D)	Wiring diagram (W)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm		Hall	mm				
12 V	0 390 203 428	7.6	4.5	145	0.5	18:1	Yes	CW/CCW	D2	W1	C1	P2

Voltage	Part number	In (Nominal current)	Fn (Nominal force)	Fmax Maximun force	Adjustment speed	Stroke	Signal	Dimensional drawing (D)	Wiring diagram (W)	Connector (C)	Performance curve (P)
		A	kN	kN	mm/s	mm	Hall				
12 V	0 390 203 399	3.3	0.5	2	9	82.0	Yes	D1	W1	C1	P1

D1



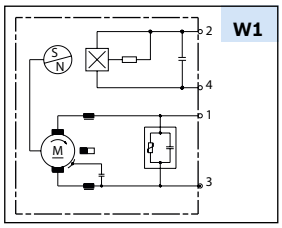
D2



AHC-D

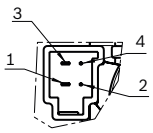
Wiring diagram (W)

W1



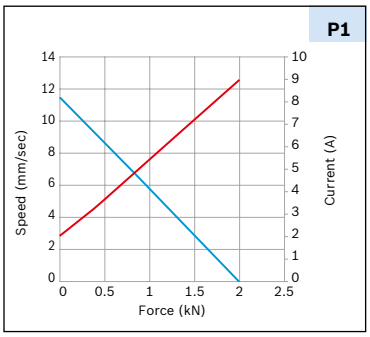
Mating connector (C)

C1

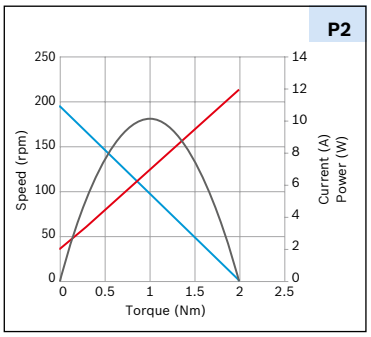


Performance curve (P)

P1



P2



D.C. motors without transmission

The Bosch D.C. motors without transmission referred to here are permanent-magnet D.C. motors developed for use in motor vehicles. They excel on account of an excellent power/weight ratio, and a broad working range in different requirements and installation situations.

Bosch electric motors without transmission are typically used in motor vehicles as a motor for heater or air-conditioning devices or for power-seat adjustment. The installation position can vary arbitrarily from horizontal to vertical. Bosch electric motors without transmission, are also the suitable solution for many applications outside the automobile.

Application examples

Automotive technology:
Heater and air-conditioning blowers, engine cooling, power-seat adjustment

Industrial applications:
Electric mopeds, house ventilation, household appliances, sweeping machines and lots more

Product features

- Wide range of permanent-magnet D.C. motor products
- D.C. voltage range from 12 to 24 Volt

Advantages for your application

- Robust and reliable quality
- High reliability and service life
- A multitude of different sizes and designs for greater flexibility
- Favorable price/performance ratio

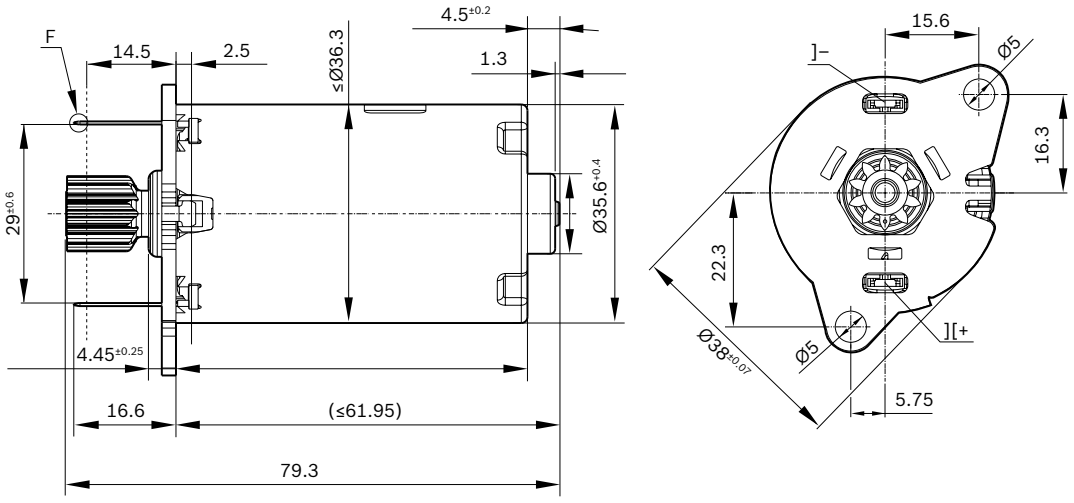
APM

Family features:

- Extended temperature range
- Operation mode: S1/S2
- Direction of rotation: CCW/CW
- Degree of protection: IP 40

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Signal	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Ncm	Ncm	Hall					
12 V	0 130 001 001	16.7	2.4	4000	4	19	No	D1	W1	S1	C1	P1

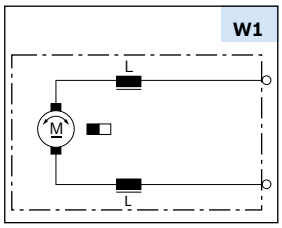
D1



APM

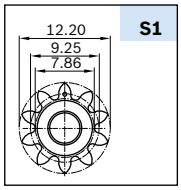
Wiring diagram (W)

W1



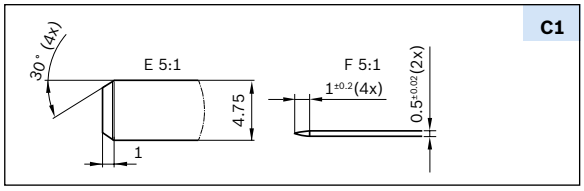
Drive end (S)

S1



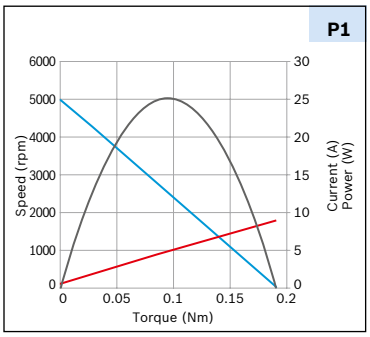
Mating connector (C)

C1

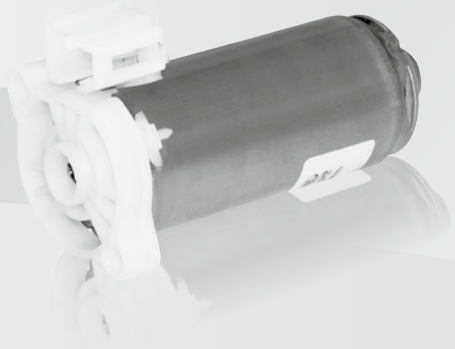


Performance curve (P)

P1



NSA-I

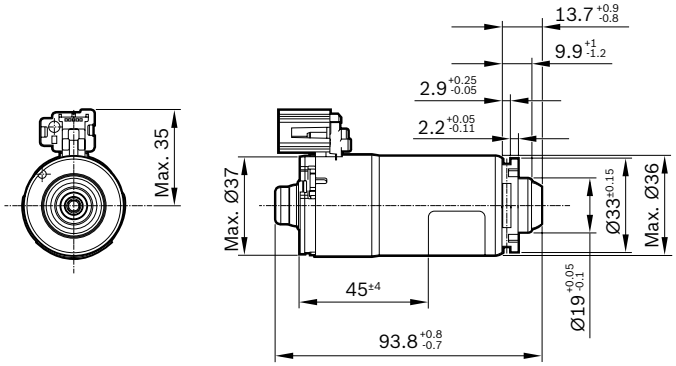


Family features:

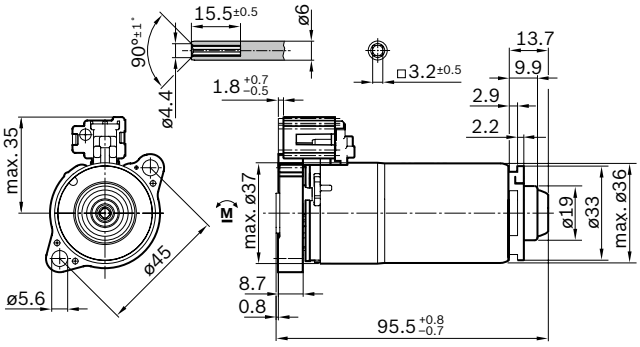
- Hall Sensor
- Degree of protection: IP 50
- Opration mode: S3
- Direction of rotation: CCW/CW
- Fit for flexi-shaft
- 2-end output

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Signal	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Ncm	Ncm	Hall					
12 V	0 390 204 092	12.6	2.5	2400	5	43	Yes	D2	W3	S1	C1	P1
	0 390 204 118	37.7	9	7200	5	48	Yes	D3	W2	S1	C1	P3
	0 390 204 166	10.4	3	3550	2.8	69	Yes	D1	W1	S1	C1	P2

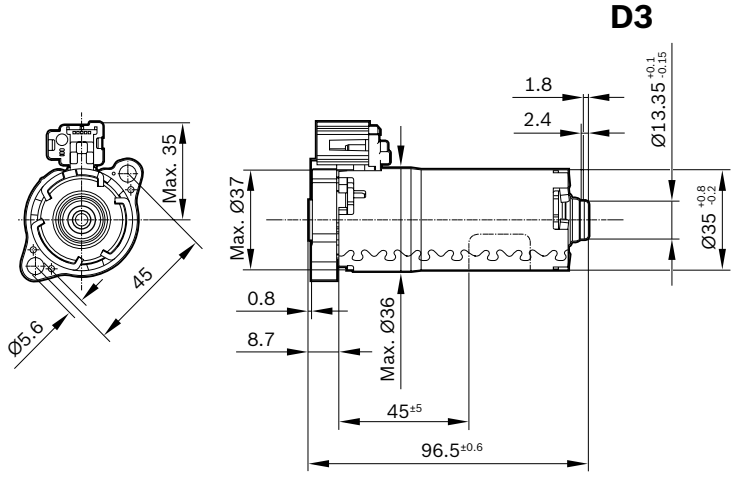
D1



D2



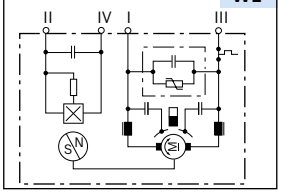
D3



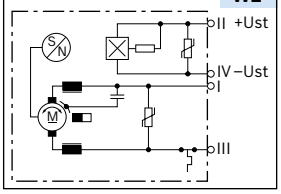
NSA-I

Wiring diagram (W)

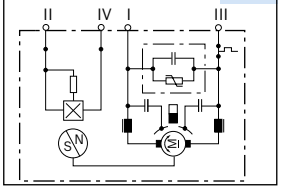
W1



W2

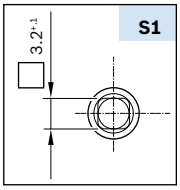


W3



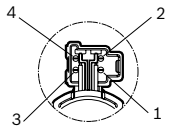
Drive end (S)

S1



Mating connector (C)

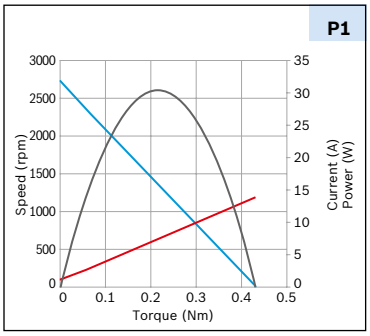
C1



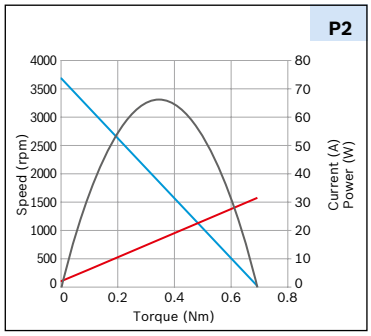
Sumitomo 4-way 6098 -2830
NBS4F – SEAT - F

Performance curve (P)

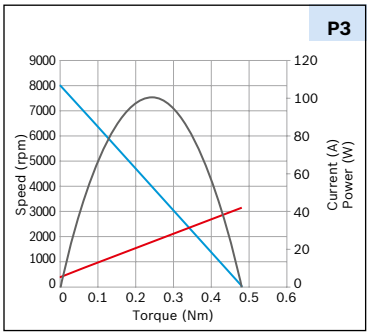
P1



P2



P3



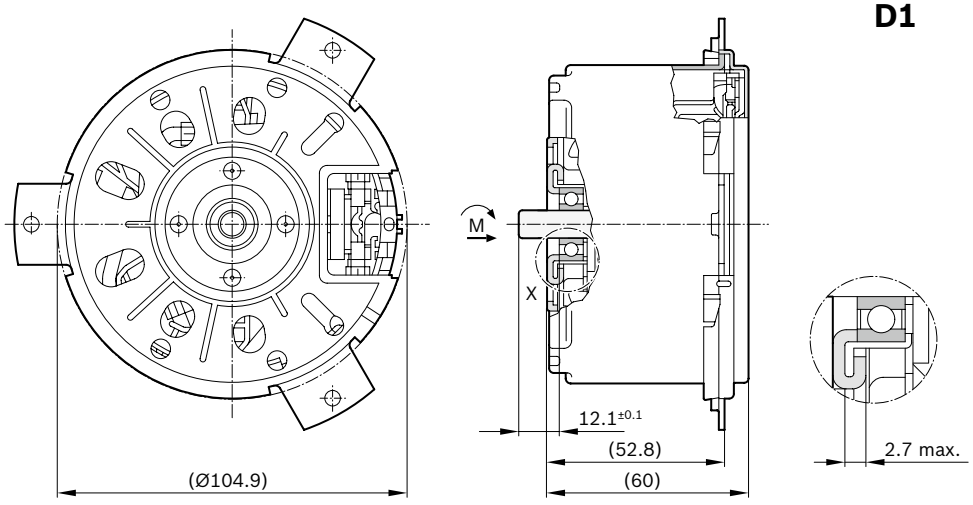
GPG-M

Family features:

- High durability and efficiency
- Degree of protection: IP 10
- Operation mode: S1
- Direction of rotation: CW

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Signal	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Perfomrance curve (P)
		W	A	rpm	Nm	Nm	Hall				
12 V	3 137 230 005	113	13	2700	0.40	3.30	No	D1	W1	S1	P1
	3 137 230 006	134	15	3200	0.40	3.50	No	D1	W1	S1	P2

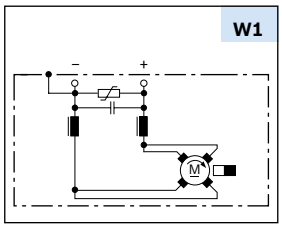
D1



GPG-M

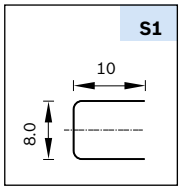
Wiring diagram (W)

W1



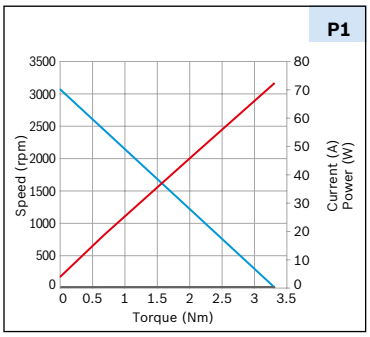
Drive end (S)

S1

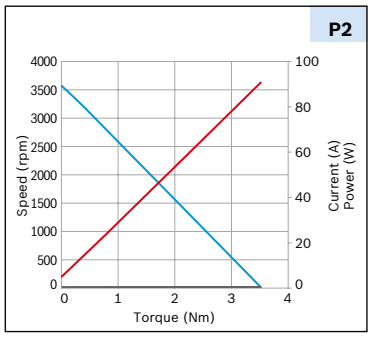


Performance curve (P)

P1



P2



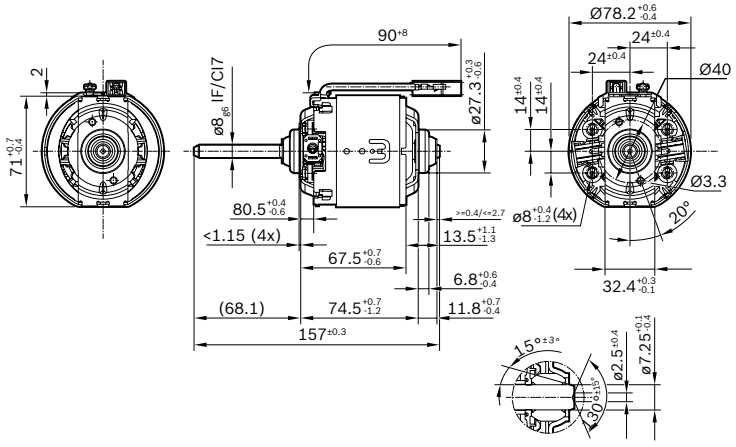
GBM

Family features:

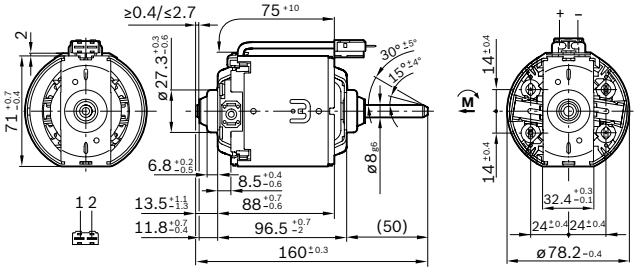
- Small, medium and large sizes
- Degree of protection: IP 10
- Operation mode: S1

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Direction of rotation	Signal	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm		Hall					
	0 130 115 352	247.5	26	4300	0.55	3.00	CW	No	D2	W1	S2	C1	P2
12 V	0 130 115 017	122.5	15	3900	0.30	1.80	CCW	No	D3	W1	S1	C1	P1
	0 130 115 008	79.5	11	3800	0.20	1.05	CCW	No	D1	W1	S3	C2	P3

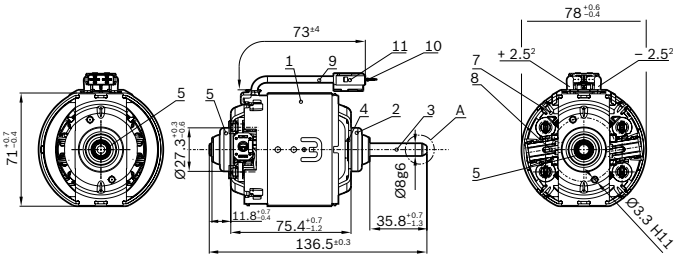
D1



D2



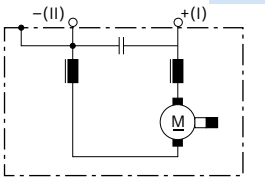
D3



GBM

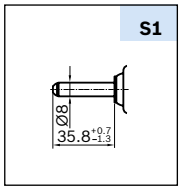
Wiring diagram (W)

W1

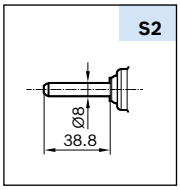


Drive end (S)

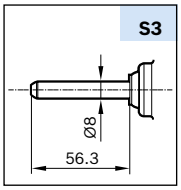
S1



S2

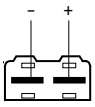


S3



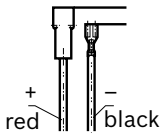
Mating connector (C)

C1



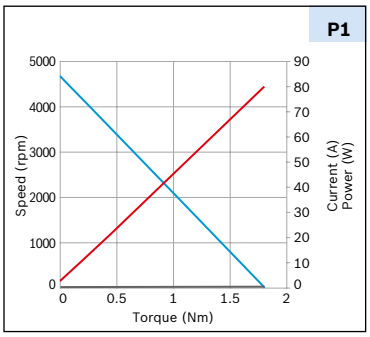
Housing: Lisi F513A
Locker: –
Terminal: Tyco 964 308-1

C2

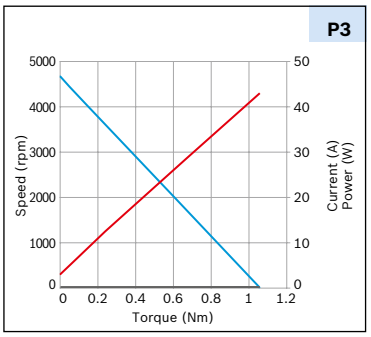


Performance curve (P)

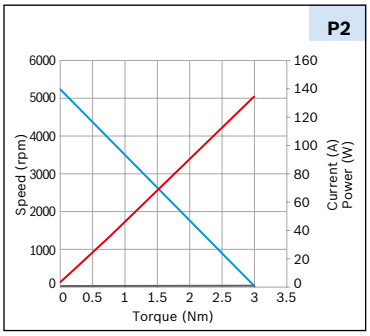
P1



P3



P2



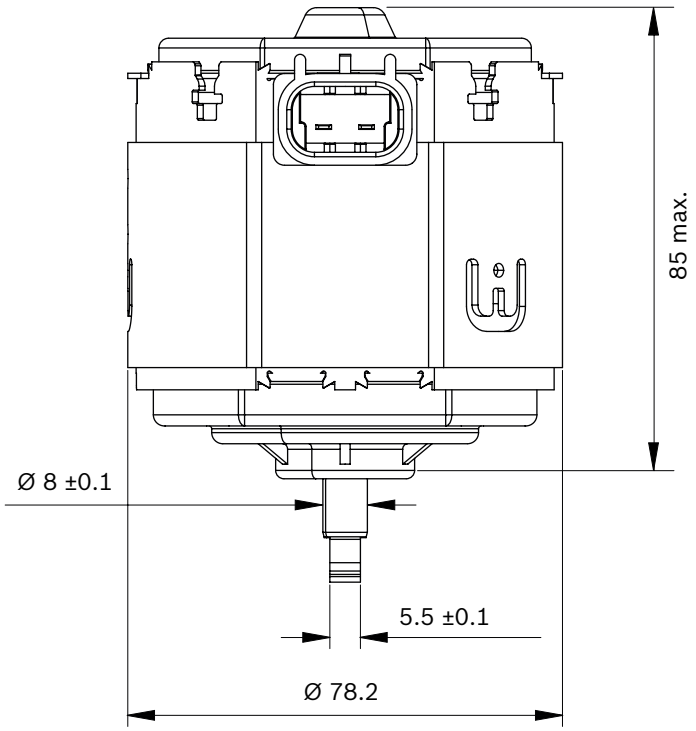
GBX

Family features:

- Small, medium and large sizes
- Degree of protection: IP 10
- Operation mode: S1

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Direction of rotation	Signal	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Connector (C)	Performance curve (P)
		W	A	rpm	Nm	Nm		Hall					
12 V	F 006 B10 440	41.8	6	1815	0.22	0.84	CW	No	D1	W1	S1	C1	P1

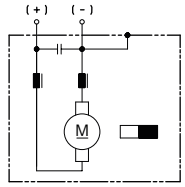
D1



GBX

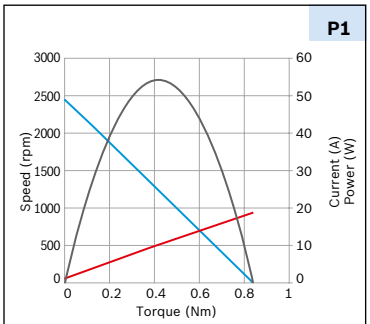
Wiring diagram (W)

W1



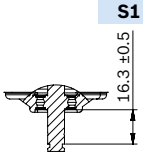
Performance curve (P)

P1



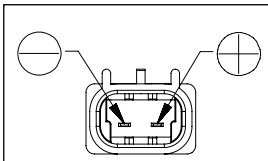
Drive end (S)

S1

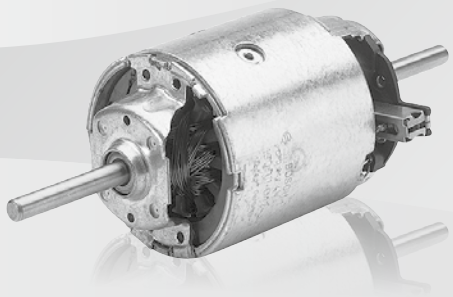


Mating connector (C)

C2



DPO-K

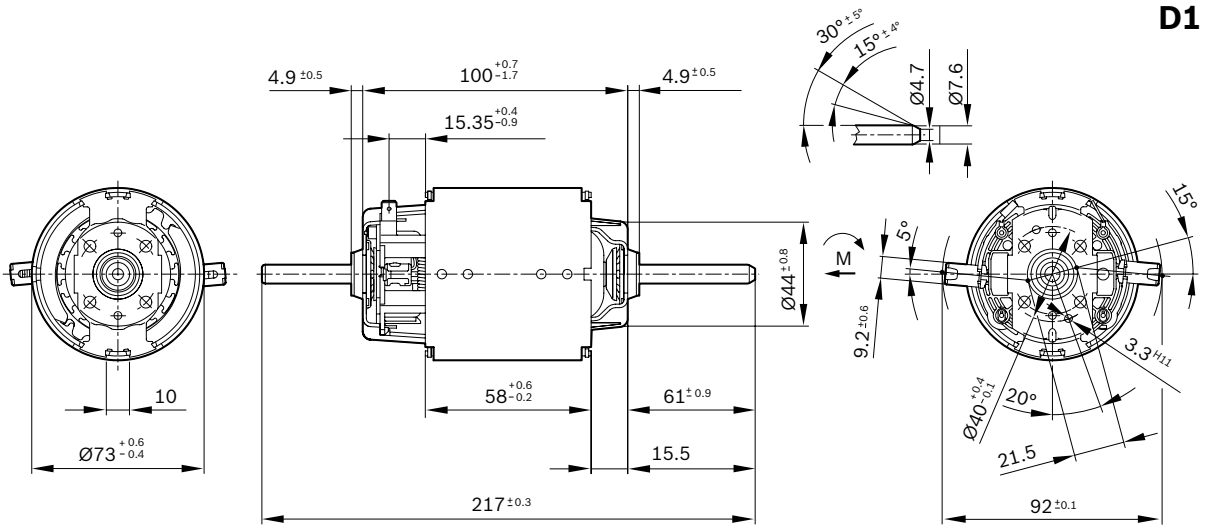


Family features:

- Long life brushes
- Fast and powerful 24 V motor
- Degree of protection: IP 10
- Operation mode: S1
- Direction of rotation: CW

Voltage	Part number	Pn (Nominal power)	In (Nominal current)	nn (Nominal speed)	Mn (Nominal torque)	Ma (Stall torque)	Signal	Dimensional drawing (D)	Wiring diagram (W)	Drive end (S)	Performance curve (P)
		W	A	rpm	Nm	Nm	Hall				
24 V	0 130 101 616	180	12	4300	0.40	2.10	No	D1	W1	S1	P1

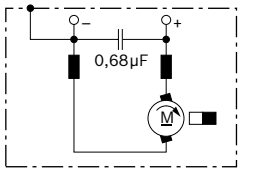
D1



DPO-K

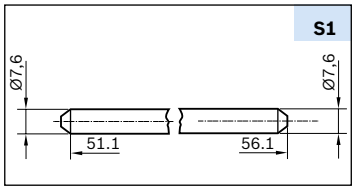
Wiring diagram (W)

W1



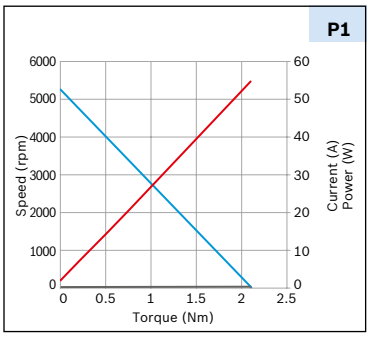
Drive end (S)

S1



Performance curve (P)

P1



Blowers and Fans with D.C. motors

As one of the largest manufacturer of electric motors in Europe, Bosch provides a comprehensive range of blower and engine-cooling products for every output range. Our blower range consists of single or multiple-stage suction or pressure blowers. The delivery range encompasses radial and axial-type blowers for 12 V and 24 V. The blowers are designed for operating mode S1 (continuous operation).
The modules are available with brush-type motors or as brushless drives.
The compact design of the modules means that they can be easily installed in areas where space is at a premium.

Automotive applications
Heating, ventilation, air-conditioning and engine cooling, cooler blowers in general

Industrial applications
Ventilation, off-highway, smart home

Product features

- Wide range of blowers and fans
- D.C. voltage range 12 V / 24 V
- Axial and radial-type blowers available
- RPM control

Advantages for your application

- Low noise development
- High efficiency
- Low weight
- Favorable price/performance ratio

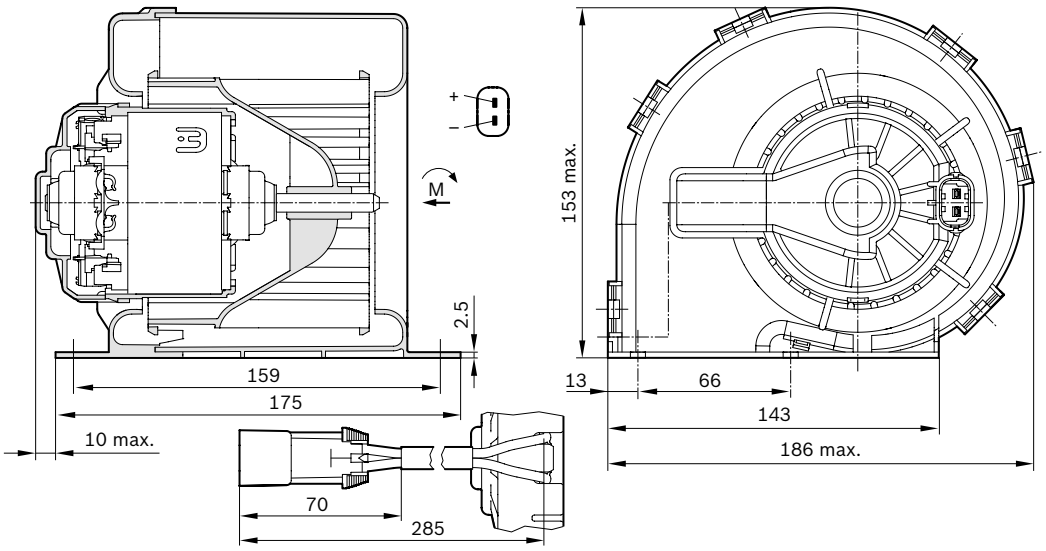
GBM-S

Family features:

- 12 V ventilation module
- Optimized noise performance
- High power density
- Operation mode: S1
- Degree of protection: IP 13

Voltage	Part number	Flow rate	Pressure difference	In (Nominal current)	nn (Nominal speed)	Direction of rotation	Signal	Dimensional drawing (D)	Wiring diagram (W)	Connector (C)	Performance curve (P)
		m3/h	Pa	A	rpm		Hall				
12 V	0 130 115 604	400	470	14	4468	CW	No	D1	W1	C1	P1

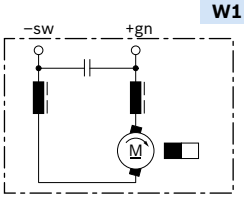
D1



GBM-S

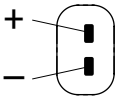
Wiring diagram (W)

W1



Mating connector (C)

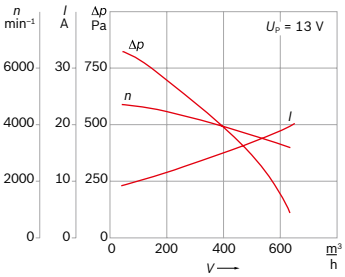
C1



Housing: Lisi F513A
Locker: –
Terminal: TE 964308-1

Performance curve (P)

P1



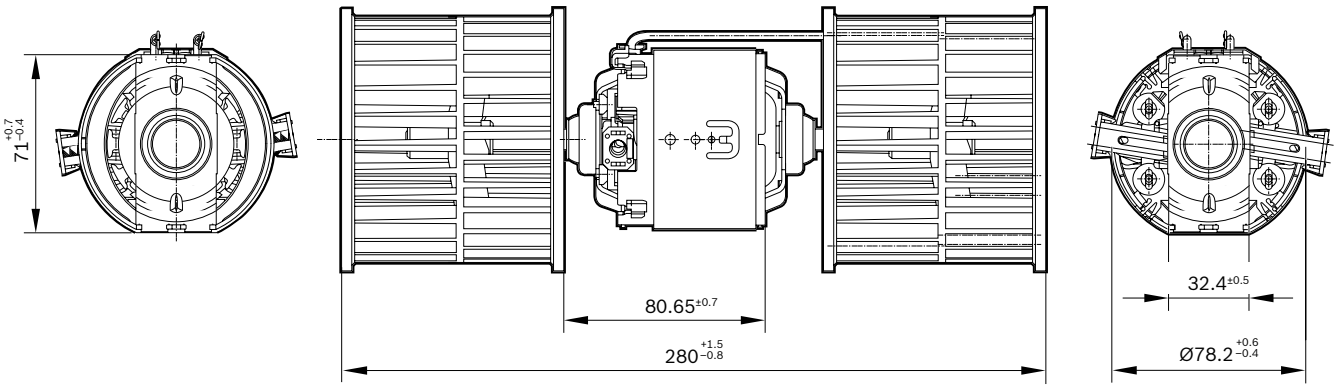
GBM-M

Family features:

- 24 V double-radial blower
- Degree of protection: IP 10
- Operation mode: S1

Voltage	Part number	Power	In Nominal current)	nn (Nominal speed)	Direction of rotation	Signal	Dimensional drawing (D)	Wiring diagram (W)	Performance curve (P)
		W	A	rpm		Hall			
24 V	F 006 B10 422	128.7	8	4100	CW	No	D1	W1	P1

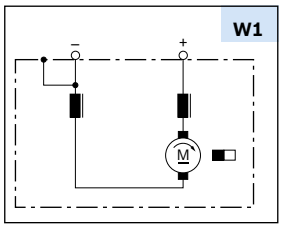
D1



GBM-M

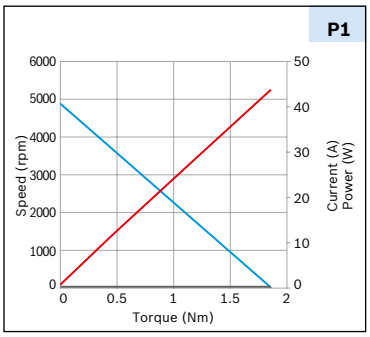
Wiring diagram (W)

W1



Performance curve (P)

P1

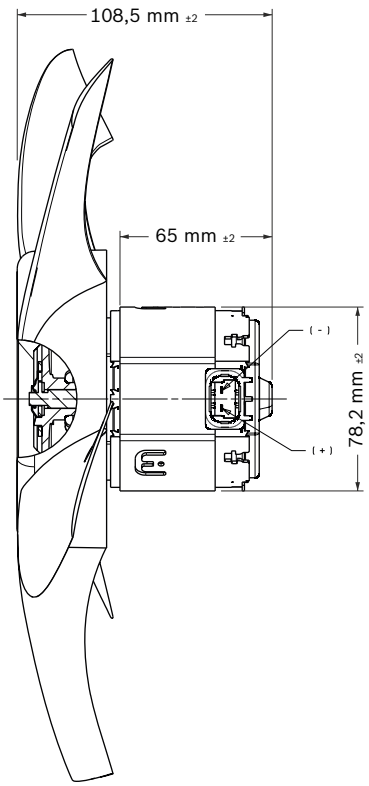


GBX

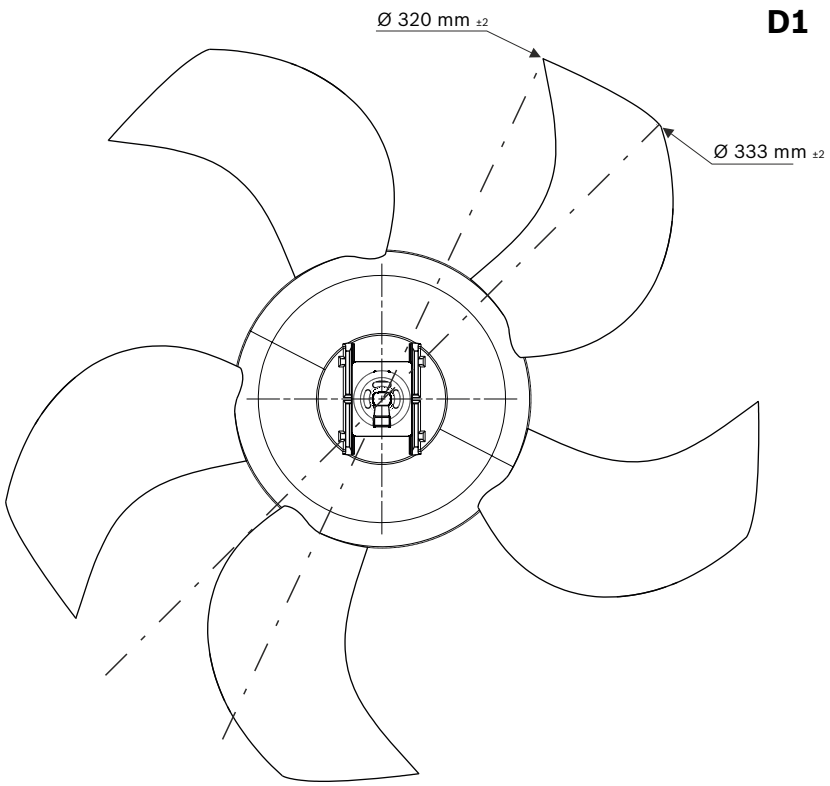
Family features:

- 12 V ventilation module
- Optimized noise performance
- High power density
- Operation mode: S1

Voltage	Part number	Power	In Nominal current)	nn (Nominal speed)	Direction of rotation	Signal	Dimensional drawing (D)	Wiring diagram (W)	Performance curve (P)
		W	A	rpm		Hall			
12 V	F 006 B10 441	41.8	6	1815	CW	No	D1	W1	P1

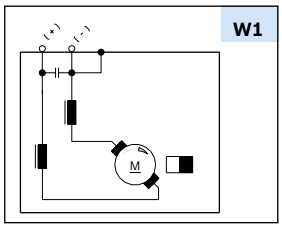


D1

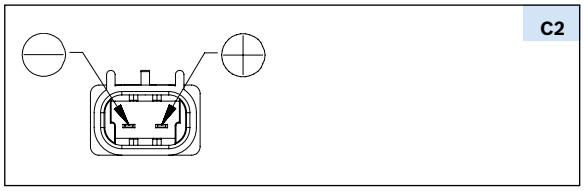


GBX

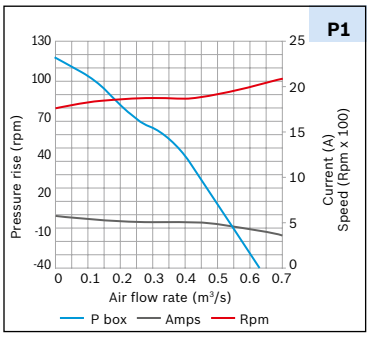
Wiring diagram (W)



Mating connector (C)



Performance curve (P)



Brushless pumps

The stator and electronics are mechanically fully-separated from the rotor in the dry motor housing. The electronics and the stator winding generate an alternating electrical magnetic field, which in turn drives the rotor. The rotor, as part of the pump wheel, is located in the separate pump housing, therefore the coolant cannot come into contact with the electronics.

Application examples

For versatile applications Bosch offers auxiliary water pumps with electronically commutated drive motors:

- Heater circuit
- Auxiliary heater
- Charge-air cooling
- Generator cooling
- Turbocharger cooling
- Fuel cooling
- After-run cooling of combustion engines
- Thermal management of electric vehicles
- Battery and electronic cooling

Advantages for your application

- Compact design
- High delivery rate
- Long service life
- High efficiency
- Silent operation

PAD

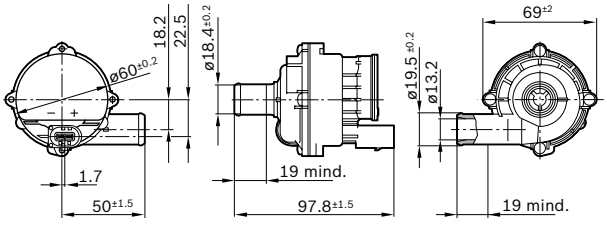
Family features:

- Silent operation
- PWM control available
- Extended temperature range available
- Extended power range available
- Degree of protection: IPX7

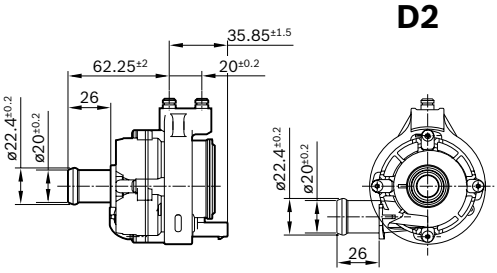
Voltage	Part number	Nominal pump pressure	Flow rate	Direction of rotation	Control	Dimensional drawing (D)	Connector (C)	Performance curve (P)
		bar	L/hr	CW or CCW				
12 V	0 392 023 232*	0.2	500	CW	PWM	D2	C2	P1
	0 392 023 004	0.1	900	CW	On / off	D1	C1	P2
	0 392 023 117**	0.1	900	CW	On / off	D3	C1	P3

* Extended power range
** Extended temperature range

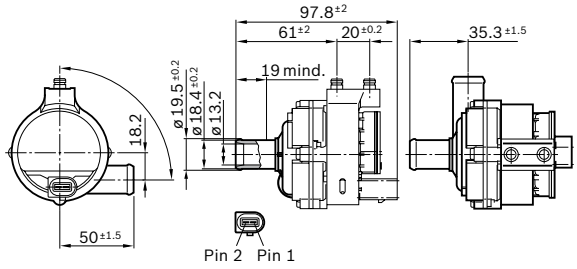
D1



D2



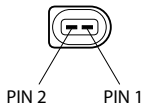
D3



PAD

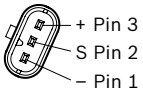
Mating connector (C)

C1



Housing: AMP 1-967412-2

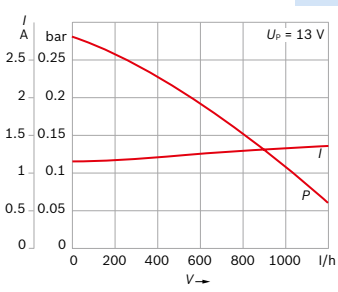
C2



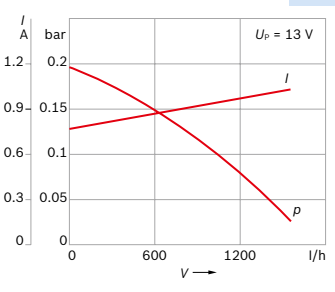
Housing: HIRSCHMAN 805-121-...00

Performance curve (P)

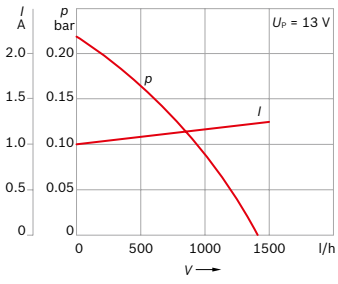
P1



P2



P3



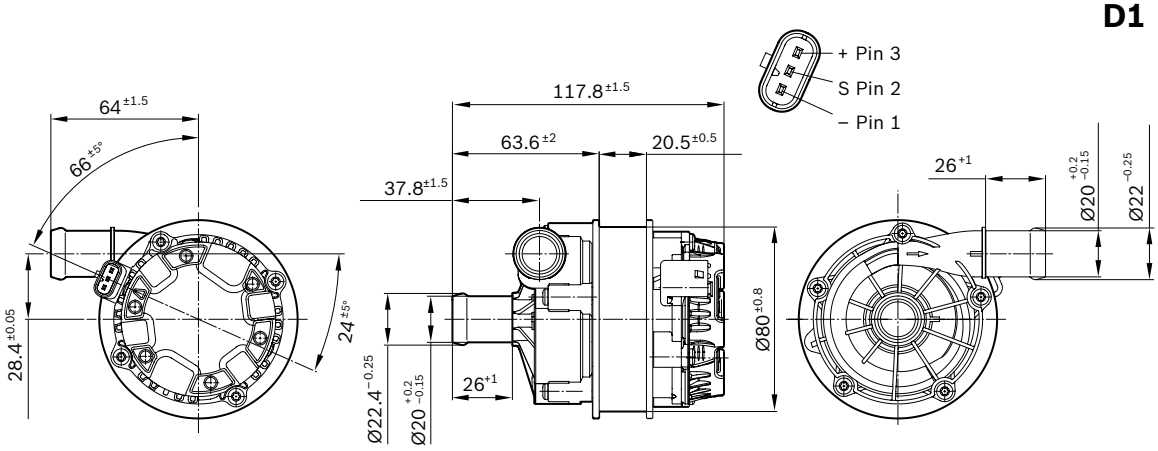
PCE

Family features:

- Silent operation
- PWM control available
- Extended temperature range available
- Extended power range available
- Degree of protection: IPX7

Voltage	Part number	Nominal pump pressure	Flow rate	Direction of rotation	Control	Dimensional drawing (D)	Connector (C)	Performance curve (P)
		bar	L/h	CW or CCW				
12 V	0 392 024 058	0.6	1200	CW	PWM	D1	C1	P1
	0 392 024 078	0.92	1000	CW	PWM	D1	C1	P2
24 V	0 392 024 041	0.6	1200	CW	PWM	D1	C1	P3

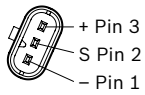
D1



PCE

Mating connector (C)

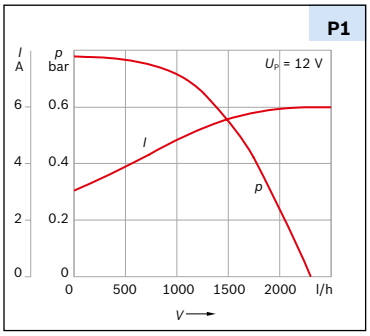
C1



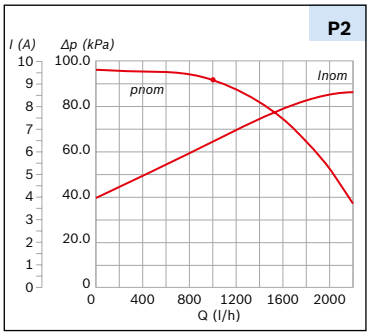
Housing: HIRSCHMAN 805-121-...00

Performance curve (P)

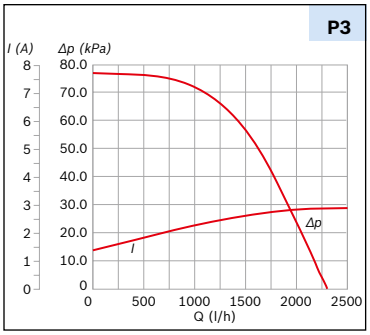
P1



P2

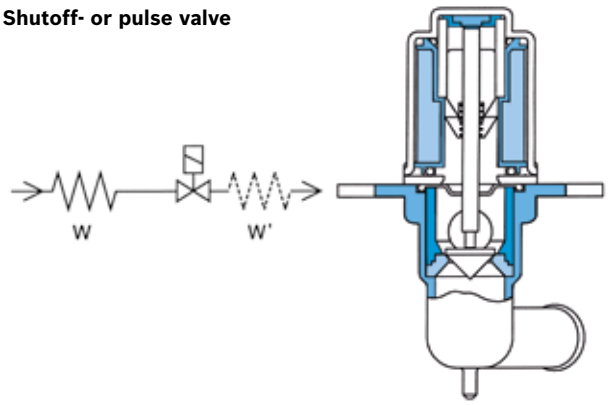


P3

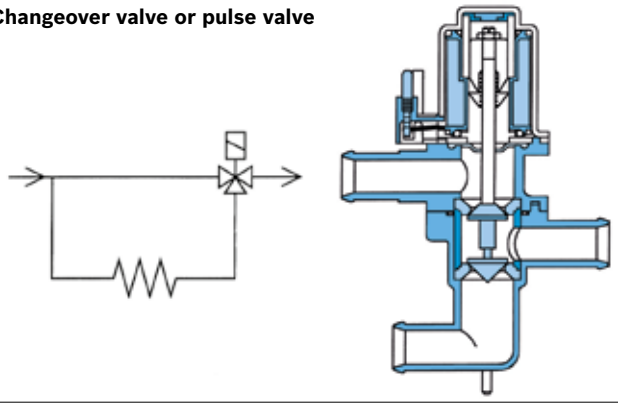


Solenoid valves

Shutoff- or pulse valve



Changeover valve or pulse valve



Valves for coolant fluids

Application

Heater control for passenger cars and commercial vehicles.

Valve models

The valves are open when de-energized.

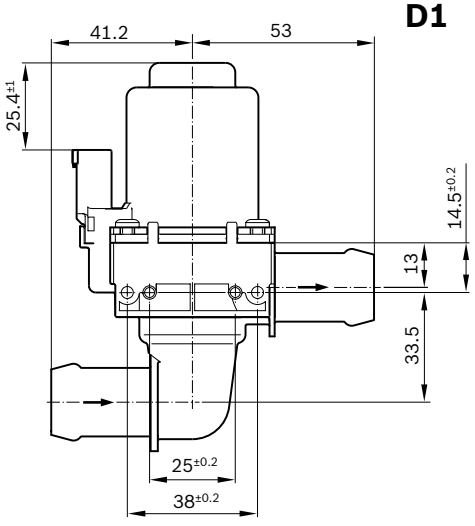
Switch-off valves

Family features:

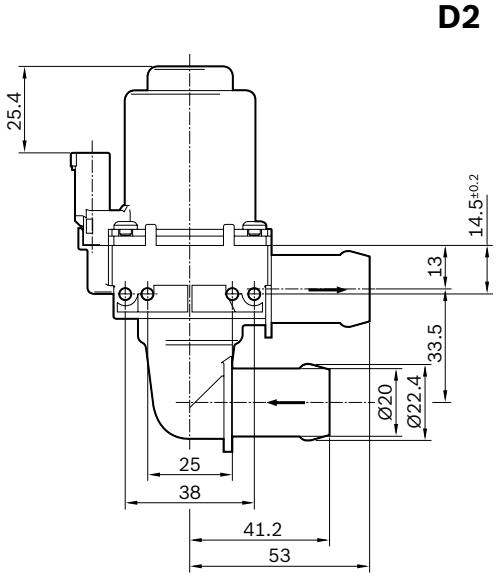
- Proportional valve function possible
- Degree of protection: IP5K4
- Open when de-energized

Voltage	Part number	Pressure drop	Flow rate	Switchable pressure difference	Resistance	Dimensional drawing (D)	Wiring diagram (W)	Connector (C)	Performance curve (P)
		kPa	L/hr	kPa	Ω				
12 V	1 147 412 208	35	1500	150	12.4	D1	W1	C1	P1
24 V	1 147 412 205	35	1500	150	48	D1	W2	C1	P1
	1 147 412 218	35	2000	160	48	D2	W2	C1	P1

D1



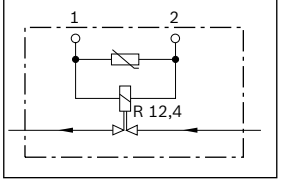
D2



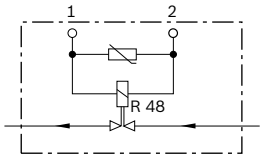
Switch-off valves

Wiring diagram (W)

W1

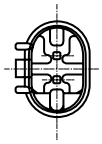


W2



Mating connector (C)

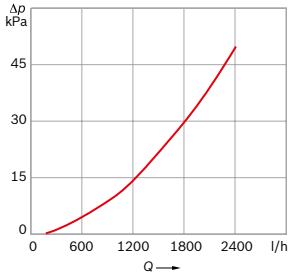
C1



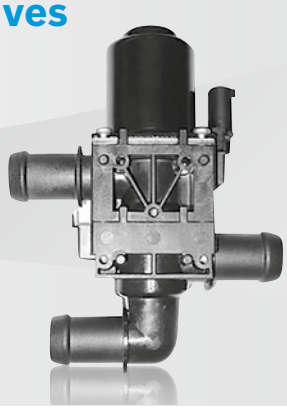
Housing: AMP 114-18063-1

Performance curve (P)

P1



Switch-over valves

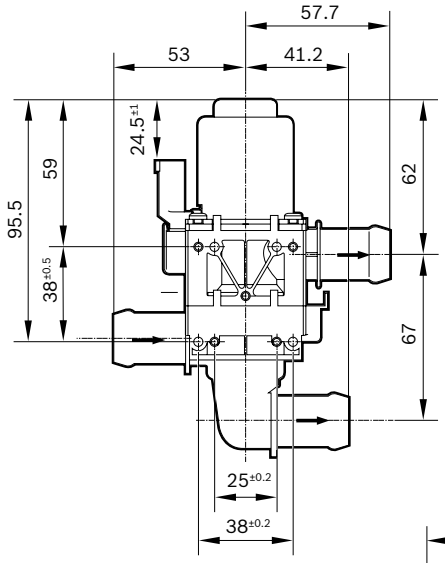


Family features:

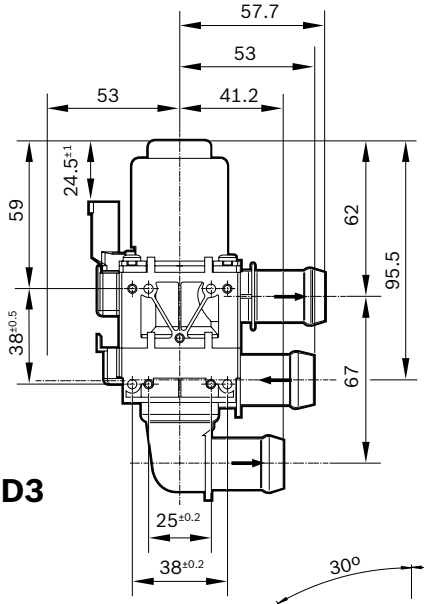
- Proportional valve function possible
- Degree of protection: IP5K4
- Open when de-energized

Voltage	Part number	Pressure drop	Flow rate	Switchabe pressure difference	Resistance	Dimensional drawing (D)	Wiring diagram (W)	Connector (C)	Performance curve (P)
		kPa	L/hr	kPa	Ω				
12 V	1 147 412 207	45	2000	60	12.4	D3	W1	C1	P1
	1 147 412 211	45	1500	160	12.4	D1	W2	C1	P2
	1 147 412 213	45	1500	160	12.4	D2	W2	C1	P2
	1 147 412 282	35	1500	160	15.3	D4	W3	C1	–
24 V	1 147 412 204	45	2000	60	48	D3	W1	C1	P1

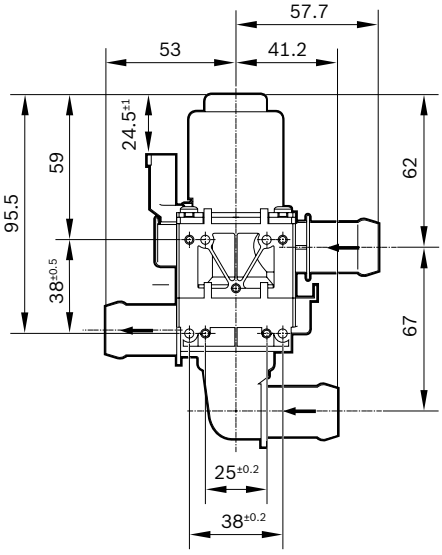
D1



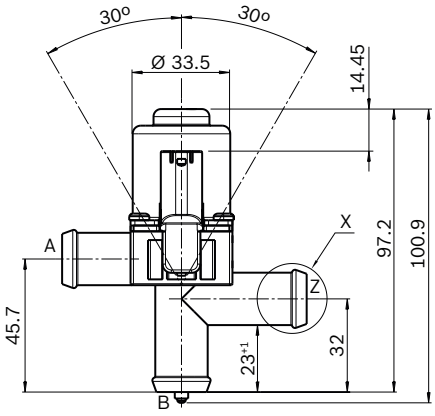
D2



D3



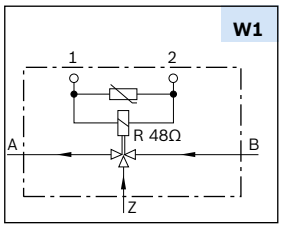
D4



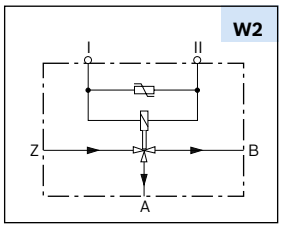
Switch-over valves

Wiring diagram (W)

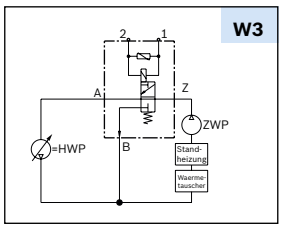
W1



W2

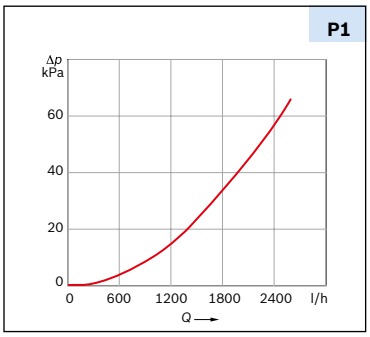


W3

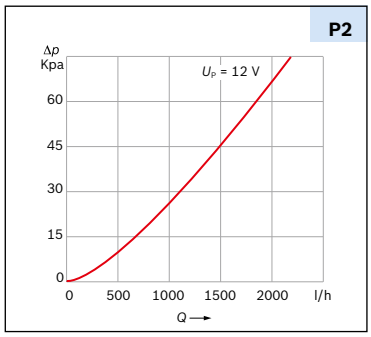


Performance curve (P)

P1

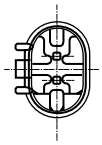


P2



Mating connector (C)

C1



Housing: AMP C-114-18063-12

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- Technical data
- Basic technical information
- Characteristic curves
- Circuit and connection diagrams
- Dimensional drawings
- 3D models

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